

Integer programming column generation:

Accelerating branch-and-price for set covering,
packing, and partitioning problems

Stephen J. Maher and Elina Rönnberg

Column generation 2023

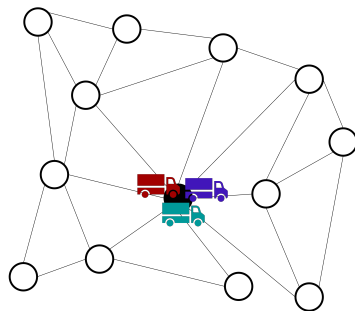
Running example: Model for VRP

Problem formulation

Use these three vehicles

Visit all customers

Minimise total travel time



Running example: Model for VRP

Compact formulation

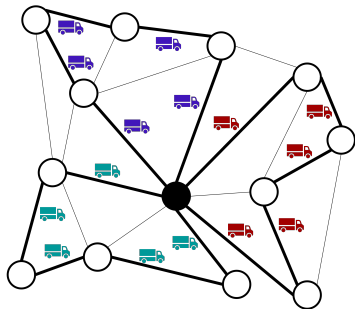
Decision variables:

$$x_{qk} = \begin{cases} 1 & \text{if vehicle } q \\ & \text{uses arc } k, \\ 0 & \text{otherwise} \end{cases}$$

Constraints:

Feasible routes for all vehicles

Vehicles cover all customers



Running example: Model for VRP

Extended formulation

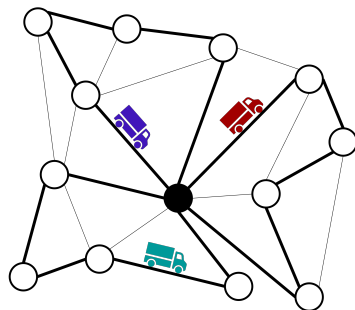
Decision variables:

$$\lambda_{qj} = \begin{cases} 1 & \text{if vehicle } q \\ & \text{uses route } j, \\ 0 & \text{otherwise.} \end{cases}$$

Constraints:

One route per vehicle

Vehicles cover all customers



Running example: Model for VRP

Extended formulation

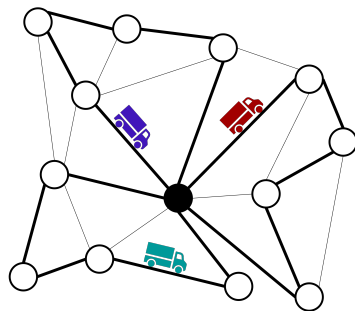
Decision variables:

$$\lambda_{qj} = \begin{cases} 1 & \text{if vehicle } q \\ & \text{uses route } j, \\ 0 & \text{otherwise.} \end{cases}$$

Constraints:

One route per vehicle

Vehicles cover all customers

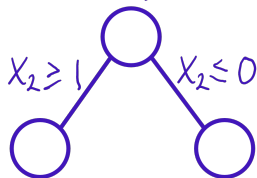


Feasible routes are constructed by solving a pricing problem

Branching for different formulations

Compact formulation

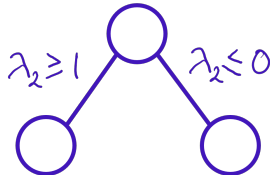
$$x = (1, 1/2)$$



$x_2 \geq 1$: Force vehicle to use arc
 $x_2 \leq 0$: Forbid vehicle to use arc

Extended formulation

$$\lambda = (1, 1/2)$$

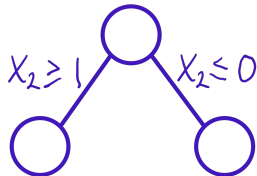


$\lambda_2 \geq 1$: Force use of route
 $\lambda_2 \leq 0$: Forbid use of route

Branching for different formulations

Compact formulation

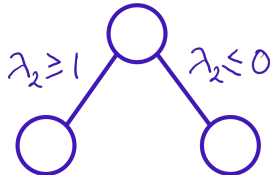
$$x = (1, 1/2)$$



$x_2 \geq 1$: Force vehicle to use arc
 $x_2 \leq 0$: Forbid vehicle to use arc

Extended formulation

$$\lambda = (1, 1/2)$$

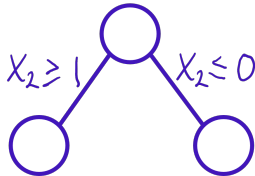


$\lambda_2 \geq 1$: Force use of route
 $\lambda_2 \leq 0$: Forbid use of route &
never generate it again

Branching for different formulations

Compact formulation

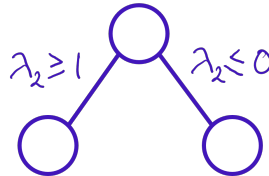
$$x = (1, 1/2)$$



$x_2 \geq 1$: Force vehicle to use arc
 $x_2 \leq 0$: Forbid vehicle to use arc

Extended formulation

$$\lambda = (1, 1/2)$$



$\lambda_2 \geq 1$: Force use of route
 $\lambda_2 \leq 0$: Forbid use of route &
never generate it again

Problem: No computationally efficient way to prevent one exact route/column/solution from being generated

Well-known challenge: Branching in branch-and-price

Instead of the "naïve" branching $\lambda_2 \geq 1$ and $\lambda_2 \leq 0$:

- ▶ Branch on variables of the corresponding compact formulation
- ▶ Translates to using or omitting one arc in the pricing problem

Common with customised branching schemes to achieve this

Well-known challenge: Branching in branch-and-price

Instead of the "naïve" branching $\lambda_2 \geq 1$ and $\lambda_2 \leq 0$:

- ▶ Branch on variables of the corresponding compact formulation
- ▶ Translates to using or omitting one arc in the pricing problem

Common with customised branching schemes to achieve this

Same type of challenge appears when designing LNS heuristics for branch-and-price, so let's return to LNS ...

Large Neighbourhood Search (LNS) heuristics

Important component in branch-and-bound-based MIP solvers
(diving, feasibility pump, local branching, ...)

- ▶ Solve an auxiliary problem to find an improved integer solution
- ▶ Also known as sub-MIPing
- ▶ Common: the auxiliary problem is formed by fixing variables

Large Neighbourhood Search (LNS) heuristics

Important component in branch-and-bound-based MIP solvers
(diving, feasibility pump, local branching, ...)

- ▶ Solve an auxiliary problem to find an improved integer solution
- ▶ Also known as sub-MIPing
- ▶ Common: the auxiliary problem is formed by fixing variables

Fixing variables to 0 yield the same issues as in the 0-branch

This is where IPColGen attempts to contribute


Outline of IPColGen

An LNS heuristic

- ▶ Destroy method:
Remove columns from a current solution
- ▶ Repair method:
 - Generate columns using a special repair pricing scheme
 - Solve a repair problem = Sub-MIP

Illustrations and VRP interpretations


Column = binary vector $(a_{ij})_{i \in I}$


$$= \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

Corresponds to a route and indicates if customer i is visited by the vehicle or not

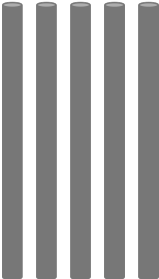
Illustrations and VRP interpretations

Column = binary vector $(a_{ij})_{i \in I}$


$$= \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

Corresponds to a route and indicates if customer i is visited by the vehicle or not


Example: feasible solution


$$= \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

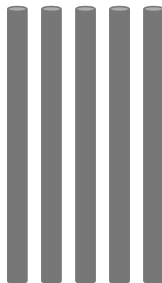
5 routes that together visit each customer exactly once

Illustrations and VRP interpretations

Column = binary vector $(a_{ij})_{i \in I}$


$$= \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

Example: feasible solution


$$= \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

Decision variables:

$$\lambda_j = \begin{cases} 1 & \text{if column } j \in \mathcal{J}_q \text{ of pricing problem } q \in Q \text{ is used,} \\ 0 & \text{otherwise} \end{cases}$$

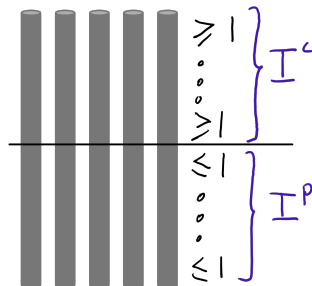
Notation

$$\begin{aligned} \text{[MP]} \quad & \min \quad \sum_{j \in \mathcal{J}} c_j \lambda_j, \\ \text{s.t.} \quad & \sum_{j \in \mathcal{J}} a_{ij} \lambda_j \geq 1, \quad i \in I^c, \\ & \sum_{j \in \mathcal{J}} a_{ij} \lambda_j \leq 1, \quad i \in I^p, \\ & (\lambda_j)_{j \in \mathcal{J}} \in \mathcal{L} \subseteq \{0, 1\}^{|\mathcal{J}|}, \end{aligned}$$

$$\mathcal{L} = \{\lambda_j \in \{0, 1\}, j \in \mathcal{J} : \sum_{j \in \mathcal{J}_q} \lambda_j = |K_q|, q \in Q\}.$$

Notation

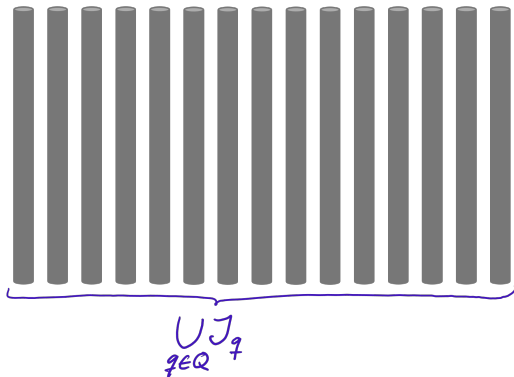
$$\begin{aligned} \text{[MP]} \quad & \min \sum_{j \in \mathcal{J}} c_j \lambda_j, \\ \text{s.t.} \quad & \sum_{j \in \mathcal{J}} a_{ij} \lambda_j \geq 1, \quad i \in I^c, \\ & \sum_{j \in \mathcal{J}} a_{ij} \lambda_j \leq 1, \quad i \in I^p, \\ & (\lambda_j)_{j \in \mathcal{J}} \in \mathcal{L} \subseteq \{0, 1\}^{|\mathcal{J}|}, \end{aligned}$$



LNS – Destroy method

Columns in RMP:

$$J_q, q \in Q$$



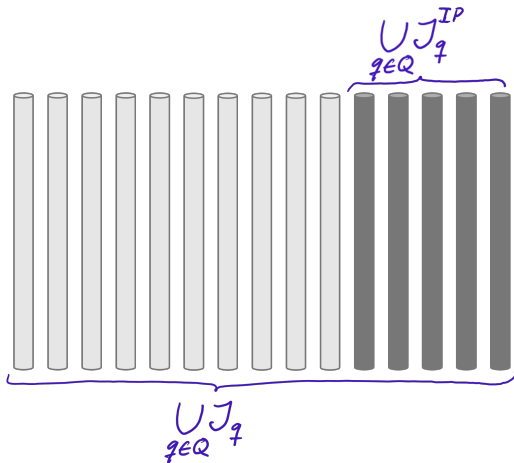
LNS – Destroy method

Columns in RMP:

$$J_q, q \in Q$$

Current solution =
active columns:

$$J_q^{IP}, q \in Q$$



LNS – Destroy method

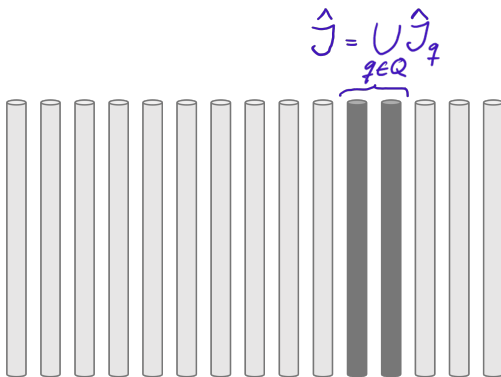
Columns in RMP:

$$J_q, q \in Q$$

Current solution =
active columns:

$$J_q^{\text{IP}}, q \in Q$$

Destroy method =
Remove active columns



LNS – Destroy method

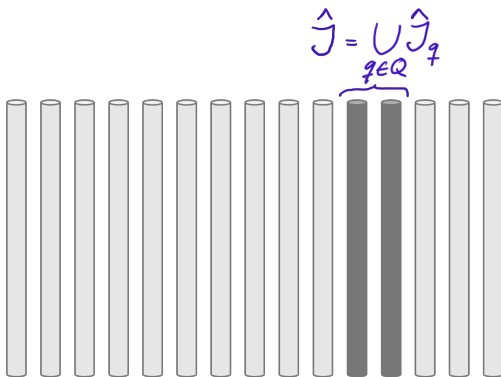
Columns in RMP:

$$J_q, q \in Q$$

Current solution =
active columns:

$$J_q^{\text{IP}}, q \in Q$$

Destroy method =
Remove active columns



Let the set of remaining columns \hat{J} be fixed:
What is the best possible way to repair the solution?

LNS – "Ideal" repair method

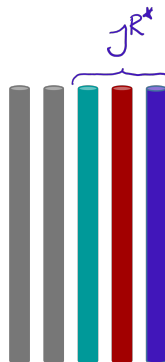
Solve [REP] over the set $J^R = \mathcal{J}$ (all possible columns)

$$\begin{aligned} \text{[REP]} \quad & \min \quad \sum_{j \in J^R} c_j \lambda_j, \\ & \text{s.t.} \quad \sum_{j \in J^R} a_{ij} \lambda_j \geq 1 - \sum_{j \in \hat{J}} a_{ij}, \quad i \in I^c, \\ & \quad \sum_{j \in J^R} a_{ij} \lambda_j \leq 1 - \sum_{j \in \hat{J}} a_{ij}, \quad i \in I^p, \\ & \quad \sum_{j \in J_q^R} \lambda_j = |K_q| - |\hat{J}_q|, \quad q \in Q, \\ & \quad \lambda_j \in \{0, 1\}, j \in J^R \cup J. \end{aligned}$$

LNS – "Ideal" repair method

Solve [REP] over the set $J^R = \mathcal{J}$ (all possible columns)

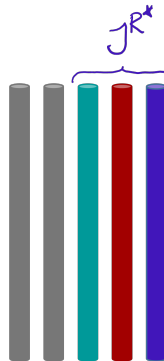
$$\begin{aligned} \text{[REP]} \quad & \min \quad \sum_{j \in J^R} c_j \lambda_j, \\ \text{s.t.} \quad & \sum_{j \in J^R} a_{ij} \lambda_j \geq 1 - \sum_{j \in \hat{J}} a_{ij}, \quad i \in I^c, \\ & \sum_{j \in J^R} a_{ij} \lambda_j \leq 1 - \sum_{j \in \hat{J}} a_{ij}, \quad i \in I^p, \\ & \sum_{j \in J_q^R} \lambda_j = |K_q| - |\hat{J}_q|, \quad q \in Q, \\ & \lambda_j \in \{0, 1\}, j \in J^R \cup J. \end{aligned}$$



LNS – "Ideal" repair method

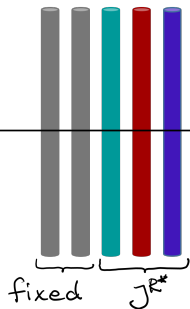
Solve [REP] over the set $J^R = \mathcal{J}$ (all possible columns)

$$\begin{aligned} \text{[REP]} \quad & \min \quad \sum_{j \in J^R} c_j \lambda_j, \\ & \text{s.t.} \quad \sum_{j \in J^R} a_{ij} \lambda_j \geq 1 - \sum_{j \in \hat{J}} a_{ij}, \quad i \in I^c, \\ & \quad \sum_{j \in J^R} a_{ij} \lambda_j \leq 1 - \sum_{j \in \hat{J}} a_{ij}, \quad i \in I^p, \\ & \quad \sum_{j \in J_q^R} \lambda_j = |K_q| - |\hat{J}_q|, \quad q \in Q, \\ & \quad \lambda_j \in \{0, 1\}, j \in J^R \cup J. \end{aligned}$$



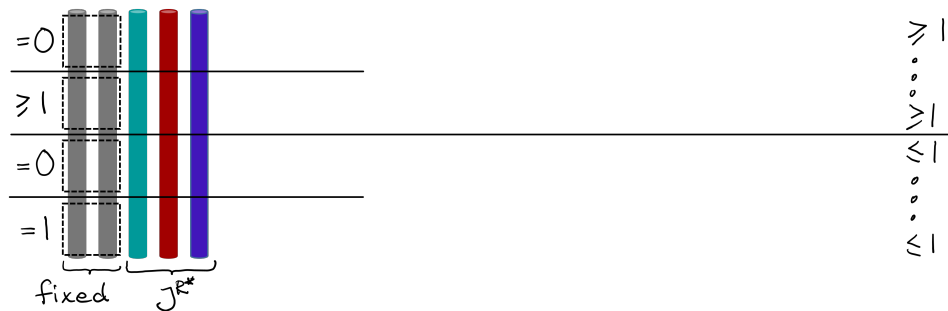
NOT reasonable in practice!

Properties of J^{R^*} and desired properties of J^R

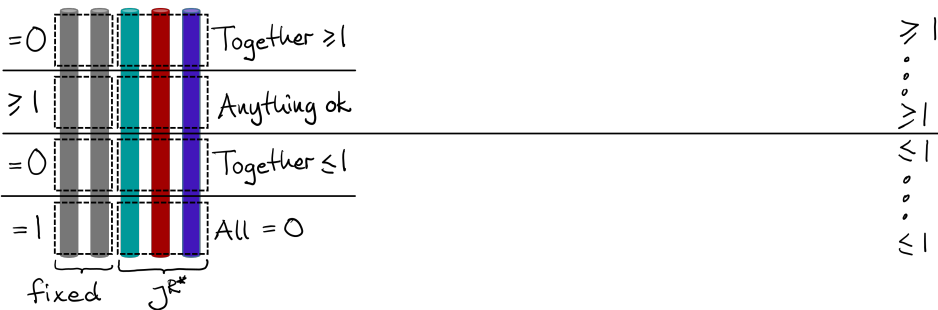


≥ 1
.
.
.
 ≥ 1
 ≤ 1
.
.
.
 ≤ 1

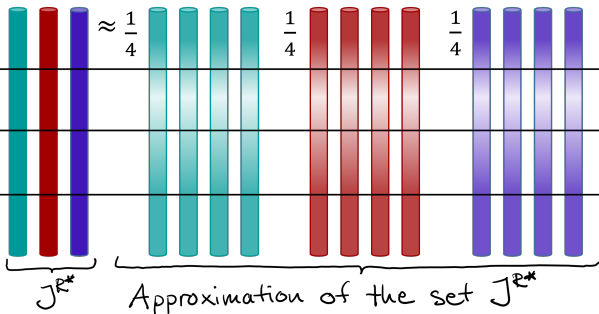
Properties of J^{R^*} and desired properties of J^R



Properties of J^{R^*} and desired properties of J^R



Properties of J^{R^*} and desired properties of J^R



Desired properties translated to the pricing problem

- ▶ "Anything ok" \Rightarrow no change in the pricing problem

Desired properties translated to the pricing problem

- ▶ "Anything ok" \Rightarrow no change in the pricing problem
- ▶ "All = 0" \Rightarrow Big- M penalty on corresponding a_i

Desired properties translated to the pricing problem

- ▶ "Anything ok" \Rightarrow no change in the pricing problem
- ▶ "All = 0" \Rightarrow Big- M penalty on corresponding a_i
- ▶ "Together ≥ 1 or ≤ 1 " \Rightarrow

Desired properties translated to the pricing problem

- ▶ "Anything ok" \Rightarrow no change in the pricing problem
- ▶ "All = 0" \Rightarrow Big- M penalty on corresponding a_i
- ▶ "Together ≥ 1 or ≤ 1 " \Rightarrow
In iteration l , aim at complying with

$$\sum_{j \in J^{R^*}} \sum_{j' \in \hat{L}_{jl}} a_{ij'} \begin{cases} \geq \frac{1}{|J^{R^*}|} \sum_{j \in J^{R^*}} |\hat{L}_{jl}|, & i \in \hat{I}^{c0}, \\ \leq \frac{1}{|J^{R^*}|} \sum_{j \in J^{R^*}} |\hat{L}_{jl}|, & i \in \hat{I}^{p0}. \end{cases}$$

Desired properties translated to the pricing problem

- ▶ "Anything ok" \Rightarrow no change in the pricing problem
- ▶ "All = 0" \Rightarrow Big- M penalty on corresponding a_i
- ▶ "Together ≥ 1 or ≤ 1 " \Rightarrow
In iteration l , aim at complying with

$$\sum_{j \in J^{R^*}} \sum_{j' \in \hat{L}_{jl}} a_{ij'} \begin{cases} \geq \frac{1}{|J^{R^*}|} \sum_{j \in J^{R^*}} |\hat{L}_{jl}|, & i \in \hat{I}^{c0}, \\ \leq \frac{1}{|J^{R^*}|} \sum_{j \in J^{R^*}} |\hat{L}_{jl}|, & i \in \hat{I}^{p0}. \end{cases}$$

**Just simple calculations and comparisons in each iteration –
adjust penalties on the corresponding a_i :s dynamically**

Repair pricing

Pricing problem q in iteration l

$$[\text{REP-CG}_{ql}] \quad \min \quad c - \sum_{i \in I^c} \bar{u}_i a_i + \sum_{i \in I^p} \bar{u}_i a_i$$

$$\text{s.t.} \quad (c, a) \in \mathcal{A}_q.$$

Repair pricing

Pricing problem q in iteration l

$$\begin{aligned} [\text{REP-CG}_{ql}] \quad \min \quad & c - \sum_{i \in I^c} \bar{u}_i a_i + \sum_{i \in I^p} \bar{u}_i a_i + \\ & + \sum_{i \in \hat{I}^{p1}} M a_i - \sum_{i \in \hat{I}^{c0}} \beta_{il} a_i + \sum_{i \in \hat{I}^{p0}} \beta_{il} a_i \\ \text{s.t.} \quad & (c, a) \in \mathcal{A}_q. \end{aligned}$$

- Static Big- M penalties and dynamic penalties β_{il}

Repair pricing

Pricing problem q in iteration l

$$\begin{aligned} [\text{REP-CG}_{ql}] \quad \min \quad & c - \sum_{i \in I^c} \gamma \bar{u}_i a_i + \sum_{i \in I^p} \gamma \bar{u}_i a_i + \\ & + \sum_{i \in \hat{I}^{p1}} M a_i - \sum_{i \in \hat{I}^{c0}} \beta_{il} a_i + \sum_{i \in \hat{I}^{p0}} \beta_{il} a_i \\ \text{s.t.} \quad & (c, a) \in \mathcal{A}_q. \end{aligned}$$

- ▶ Static Big- M penalties and dynamic penalties β_{il}
- ▶ Adjust the reduced costs with the parameter $\gamma \in [0, 1]$

Y. Zhao, T. Larsson, E. Rönnberg.

An integer programming column generation principle for heuristic search methods.

International Transactions in Operational Research, 27:665–695, 2020.

Implementation in GCG module of SCIP

IPColGen is implemented as part of the B&P&C scheme in GCG

- ▶ Apply in root node

Implementation in GCG module of SCIP

IPColGen is implemented as part of the B&P&C scheme in GCG

- ▶ Apply in root node when
 - when tailing-off for the LP-relaxation begins

Implementation in GCG module of SCIP

IPColGen is implemented as part of the B&P&C scheme in GCG

- ▶ Apply in root node when
 - when tailing-off for the LP-relaxation begins
 - optimality gap is large (= expected to be of most use)

Implementation in GCG module of SCIP

IPColGen is implemented as part of the B&P&C scheme in GCG

- ▶ Apply in root node when
 - when tailing-off for the LP-relaxation begins
 - optimality gap is large (= expected to be of most use)
- ▶ Apply for a subset of the nodes in the B&P tree
(too expensive to use in all nodes)

Implementation in GCG module of SCIP

IPColGen is implemented as part of the B&P&C scheme in GCG

- ▶ Apply in root node when
 - when tailing-off for the LP-relaxation begins
 - optimality gap is large (= expected to be of most use)
- ▶ Apply for a subset of the nodes in the B&P tree
(too expensive to use in all nodes)

Evaluated when used in addition to all other heuristics in
GCG/SCIP to compare to its state of the art

Evaluation measures

- ▶ All results as a function of first call gap

Evaluation measures

- ▶ All results as a function of first call gap
- ▶ Primal integral
 - Common way to measure progress of heuristics
 - Each point in time: integral over primal gap as function of time
- ▶ Primal / optimality gap after 3,600s

Evaluation measures

- ▶ All results as a function of first call gap
- ▶ Primal integral
 - Common way to measure progress of heuristics
 - Each point in time: integral over primal gap as function of time
- ▶ Primal / optimality gap after 3,600s
- ▶ Diverse test set:
Shifted geometric mean
- ▶ Display ratio with/without IPColGen

Evaluation measures

- ▶ All results as a function of first call gap
- ▶ Primal integral
 - Common way to measure progress of heuristics
 - Each point in time: integral over primal gap as function of time
- ▶ Primal / optimality gap after 3,600s
- ▶ Diverse test set:
Shifted geometric mean
- ▶ Display ratio with/without IPColGen

*Essentially:
A value < 1
means we
perform well*



Instances with known block diagonal structures

Results for about 700 instances

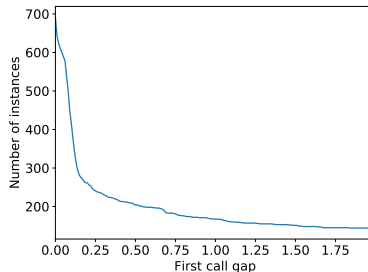
- ▶ Bin packing
- ▶ Capacitated p-median
- ▶ Generalised assignment
- ▶ Vertex coloring
- ▶ Optimal interval scheduling

Instances with known block diagonal structures

Results for about 700 instances

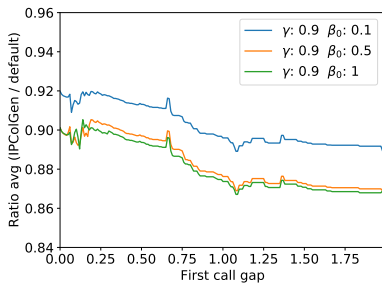
- ▶ Bin packing
- ▶ Capacitated p-median
- ▶ Generalised assignment
- ▶ Vertex coloring
- ▶ Optimal interval scheduling

Instance characteristics



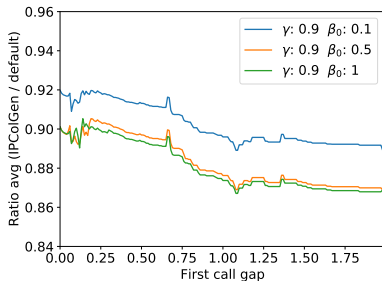
Results: Instances with known block diagonal structures

Final optimality gap

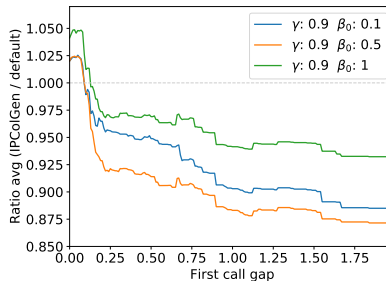


Results: Instances with known block diagonal structures

Final optimality gap

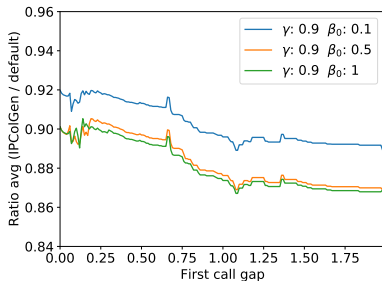


Primal integral

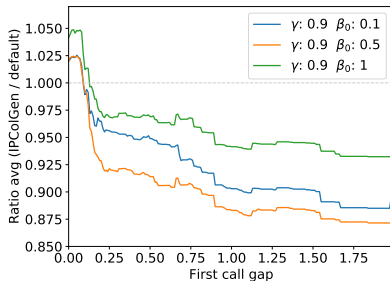


Results: Instances with known block diagonal structures

Final optimality gap



Primal integral



- ▶ better primal solutions + better final gap for all instances
- ▶ better primal integral only for instances with large initial gap

Instances from MIPLIB 2017

Results for about 160 instances
with known solution and tags

- ▶ Decomposition
- ▶ Set covering
- ▶ Set packing
- ▶ Set partitioning

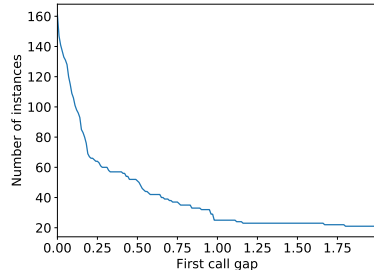
Automatic structure detection & D-W decomposition in GCG

Instances from MIPLIB 2017

Results for about 160 instances with known solution and tags

- ▶ Decomposition
- ▶ Set covering
- ▶ Set packing
- ▶ Set partitioning

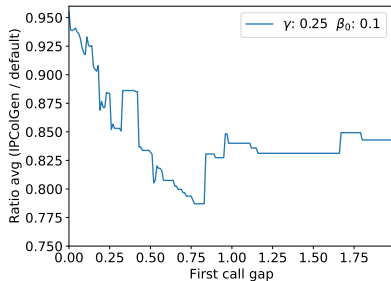
Instance characteristics



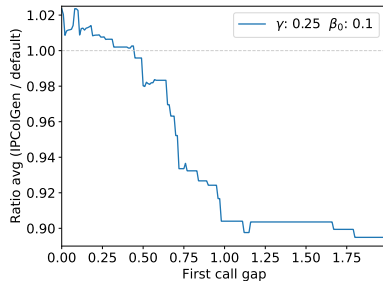
Automatic structure detection & D-W decomposition in GCG

Results: Instances from MIPLIB 2017

Final primal gap

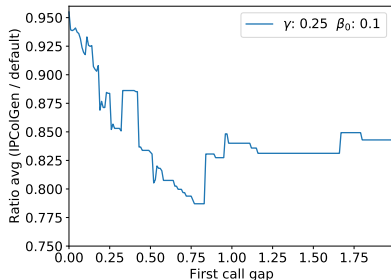


Primal integral

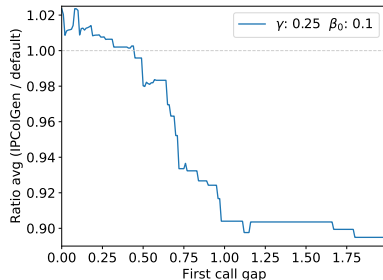


Results: Instances from MIPLIB 2017

Final primal gap



Primal integral



Same type of results as for instances with known structure!

Conclusions

**IPColGen behaves as intended:
Helps GCG/SCIP finding high-quality integer solutions &
improves computational performance for difficult instances**

Conclusions

**IPColGen behaves as intended:
Helps GCG/SCIP finding high-quality integer solutions &
improves computational performance for difficult instances**

Paper also includes

- ▶ Detailed derivation of pricing scheme
- ▶ More tests + performance measures
- ▶ Analysis for different parameter settings
- ▶ An extension of the restricted master heuristic

Room for several improvements of both theory and implementation

Open positions on the horizon

- ▶ **Assistant Professor in non-linear programming**
 - Needs to be a touch of AI, e.g. optimisation for learning
 - Funding: 80% research in 5 years + PhD student or 2 postdocs
- ▶ **Any type of Professor in MIP/discrete optimisation**
 - Preferably someone who wants to collaborate with me =)
 - Nice if interested in combining with data-driven methods and has interest in both theory, methods and applications
 - Funding: 80% research in 5 years +
can take part in projects/supervision in my group

Both are permanent positions

(as Assistant professor you can get kicked out after 5 years if duties are neglected)

I need to get in contact with candidates before announcing!