

# solar: A solar thermal power plant simulator for blackbox optimization benchmarking

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### **Presentation outline**

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### Contributors

- ▶ This work is based on the MSc thesis of [Lemyre Garneau, 2015]
- The other contributors are
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  - Bastien Talgorn
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  - Christophe Tribes



# **Context: Blackbox Optimization (BBO)**

$$\min_{\mathbf{x}\in\mathcal{X}} \quad F(\mathbf{x}) \text{ s.t. } \mathbf{x}\in\Omega = \{\mathbf{x}\in\mathcal{X}: c_j(\mathbf{x})\leq 0, j=1,2,\ldots,m\}$$

 $\mathcal{X}$  is a *n*-dimensional space, *F* can have p = 1 or p = 2 components, and the evaluations of *F* and the  $c_i$ 's are provided by a blackbox:

$$\begin{array}{c} \mathbf{x} \in \mathcal{X} \\ \hline \text{if (i!=hat_i)} \\ n \text{ inputs} \end{array} \xrightarrow{\text{for (i=0; i < nc; ++i)}}_{\substack{\text{if (i!=hat_i)} \\ j = rp.pickup(); \\ j = rp.pickup(); \\ j = rp.pickup(); \\ \end{array}} F(\mathbf{x}), c_j(\mathbf{x}), j = 1, 2, \dots, m$$

- Each call to the blackbox may be expensive
- The evaluation can fail
- Sometimes  $F(\mathbf{x}) \neq F(\mathbf{x})$
- Derivatives are not available and cannot be approximated



# **Objectives of this work**

Provide a realistic application for "true" BBO benchmarking, that

- is easy to install (stand-alone, standard code)
- is multiplatform
- allows to reproduce results
- includes many options allowing to
  - test different aspects of BBO such as
    - time-consuming evaluations
    - discrete/categorical variables
    - constraints handling
    - noise in the blackbox outputs
    - static surrogates
    - multiobjective optimization
  - propose sets of instances to draw performance/data profiles

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### CSP power plant with molten salt thermal energy storage

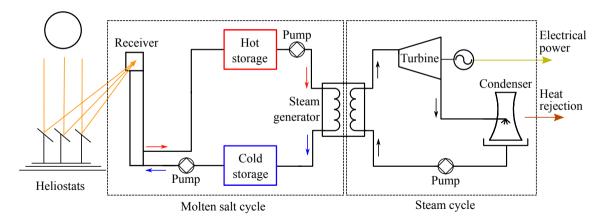
- A large number of mirrors (heliostats) reflects solar radiation on a receiver at the top of a tower
- The heat collected from the concentrated solar flux is removed from the receiver by a stream of molten salt
- Hot molten salt is then used to feed thermal power to a conventional power block
- The photo shows the Thémis CSP power plant, the first built with this design

Source: https://commons.wikimedia.org/wiki/File:Themis\_2.jpg



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### **System dynamics**



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### The solar code is

- a command-line application
- ▶ the "natural heir" of our STYRENE simulator [Audet et al., 2008]
- publicly available at https://github.com/bbopt/solar under the GNU Lesser General Public License
- ▶ a relatively simple code in standard C++ ( $\simeq$ 15k lines of codes)
- stand-alone: no external library to install
- multi-platform: C++ compilator is the only requirement

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### **Ten instances**

Instance	#	of variables		# of obj.	#	of constraints		# of stoch. outputs	Static
	cont.	discr. (cat.)	n	p	simu.	a priori (lin.)	m	(obj. or constr.)	surrogate
solar1	8	1 (0)	9	1	2	3 (2)	5	1	no
solar2 <sup>1</sup>	12	2 (0)	14	1	9	4 (2)	13	3	yes
solar3	17	3 (1)	20	1	8	5 (3)	13	5	yes
solar4	22	7 (1)	29	1	9	7 (5)	16	6	yes
solar5	14	6 (1)	20	1	8	4 (3)	12	0	no
solar6	5	0 (0)	5	1	6	0 (0)	6	0	no
solar7	6	1(0)	7	1	4	2 (1)	6	3	yes
solar8	11	2 (0)	13	2	4	5 (3)	9	3	yes
solar9	22	7 (1)	29	2	10	7 (5)	17	6	yes
solar10 <sup>2</sup>	5	0 (0)	5	1	0	0 (0)	0	0	yes

<sup>1</sup>analytic objective <sup>2</sup>unconstrained

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Types of	variables				
	$\min_{\mathbf{x}\in\mathcal{X}}  F(\mathbf{x}) s$	t. $\mathbf{x} \in \Omega = {\mathbf{x} \in Z}$	$\mathcal{X}: c_j(\mathbf{x}) \le 0, j =$	$1, 2, \ldots, m\}$	

- $\blacktriangleright$  The *n* variables are described by the set  $\mathcal{X}$ . They can be continuous or discrete
- $\blacktriangleright$   ${\cal X}$  includes bounds on most of the variables
- ▶ There are 29 possible variables. Each instance considers a subset of these variables. solar4 and solar9 consider all n = 29 variables
- $\blacktriangleright$  The solar6 and solar10 instances have no discrete variables. In these cases  $\mathcal{X} \subset \mathbb{R}^5$
- One of the discrete variable (the type of turbine) is categorical. solar considers it as an integer in {1,2,...,8}

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Types of	constraints				

 $\min_{\mathbf{x}\in\mathcal{X}} \quad F(\mathbf{x}) \text{ s.t. } \mathbf{x}\in\Omega = \{\mathbf{x}\in\mathcal{X}: c_j(\mathbf{x})\leq 0, j=1,2,\ldots,m\}$ 

- X describes bounds on the variables and the discrete nature of some of the variables. These constraints are unrelaxable
- $\blacktriangleright$  The m constraints in  $\Omega$  may be a priori or simulation constraints
- A priori constraints are also unrelaxable. In case of violation, the solar executable returns a flag to indicate a potential solver not to count the evaluation
- Most of the a priori constraints are linear
- Simulation constraints are relaxable
- Presence of hidden constraints
- All constraints (except the hidden ones) are quantifiable
- There are 18 possible constraints. Each instance considers a subset of these constraints, for a maximum of m = 17 constraints in solar9

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### Getting started with solar

- Get the code at https://github.com/bbopt/solar and compile
- Command-line program that takes as arguments
  - ▶ a problem id (or instance number) in  $\{1, 2, ..., 10\}$
  - $\blacktriangleright$  the name of a file containing the coefficients of a point  ${\bf x}$

and displays the values of  $F(\mathbf{x})$  and the  $c_j(\mathbf{x})$ 's

- Example: > solar 7 x.txt displays f c1 c2 ... c6 (objective and six constraints)
- Simply executing > solar will guide the user and display the options, including a complete inline help with > solar -help

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### Check the solar installation

#### > solar -check

Mac: Intel Core i9: 659s Apple M1 Pro: 451s Apple M1 Max: 444s Apple M2 Max: 393s

Windows: Intel Core i7-7700: 2,684s

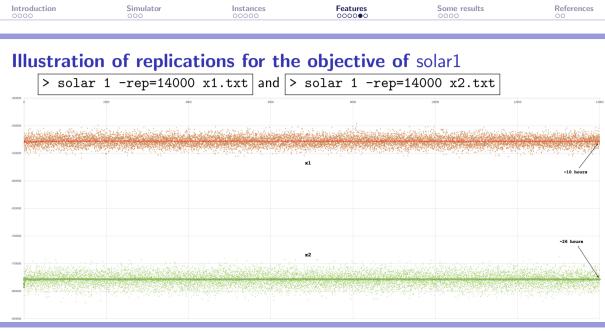
Linux: AMD EPYC-7402: 1,284s Intel Core i7-12700: 349s

[[12:34:11] [~/Desktop] > .	/solar -chec	k		
Validation tests (can take	several min	utes):		
		,-		
RNG test (1/2)	Ok	Time: C	PU=8.8e-05	real=0
RNG test ( 2/ 2)	Ok	Time: C	PU=9e-06	real=0
Eval test ( 1/26)		Time: C	PU=0.090865	real=0
Eval test ( 2/26)	Ok	Time: C	CPU=0.164074	real=0
Eval test ( 3/26)	Ok	Time: C	CPU=8.55466	real=9
Eval test ( 4/26)	Ok	Time: C	CPU=14.3939	real=14
Eval test ( 5/26)	Ok	Time: C	CPU=12.444	real=12
Eval test ( 6/26)	Ok	Time: C	CPU=1.67694	real=2
Eval test ( 7/26)	Ok	Time: C	CPU=1.714	real=2
Eval test ( 8/26)	Ok	Time: C	CPU=0.000297	real=0
Eval test ( 9/26)	Ok	Time: C	CPU=1.8335	real=2
Eval test (10/26)	Ok	Time: C	CPU=16.9975	real=17
Eval test (11/26)	Ok	Time: C	CPU=0.088462	real=0
Eval test (12/26)			CPU=1.76882	real=2
Eval test (13/26)			CPU=2.03457	real=2
Eval test (14/26)			CPU=57.289	real=57
Eval test (15/26)			CPU=76.4028	real=76
Eval test (16/26)			CPU=2.17247	real=2
Eval test (17/26)			CPU=50.1873	real=51
Eval test (18/26)			CPU=50.3843	real=50
Eval test (19/26)			CPU=50.3955	real=50
Eval test (20/26)			CPU=3.31858	real=4
Eval test (21/26)			CPU=3.21749	real=3
Eval test (22/26)			CPU=5.77947	real=6
Eval test (23/26)			CPU=0.003279	real=0
Eval test (24/26)			CPU=3.86108	real=4
Eval test (25/26)			CPU=2.24941	real=2
Eval test (26/26)	Ok	Time: C	CPU=25.7252	real=26
This version of SOLAR is v	alid			
CPU time : 392.748s				
Real time: 393s				



## **Stochasticity and replications**

- Stochasticity is due to the Monte Carlo simulation for the heliostats field
- Random seed is set to the same value by default: This corresponds to a deterministic blackbox
- Use the option -seed to change the random seed
- ► The option -seed=diff makes the blackbox stochastic
- ► The option -rep executes several simulations and outputs average values
- A high number of replications will tend to decrease stochasticity but will lead to expensive evaluations (which is great in BBO benchmarking)



#### solar: github.com/bbopt/solar

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# **Multi-fidelity**

- ▶ The option -fid with a value in ]0;1] changes the fidelity of the simulator
- Each different value of this option generates a static surrogate
- -fid=1 corresponds to the "true" blackbox (called the truth)
- This option allows to consider multi-fidelity metamodels or variable precision static surrogates
- Note that using the <u>-rep</u> option also allows to consider such surrogates when the truth is considered to be obtained with high number of replications

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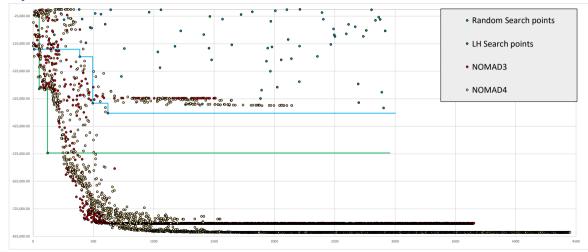
## Feasibility with sampling and NOMAD

Instance	LH search (10k points)		NOMAD3		
	satisf. ap constr.	feas. pts	satisf. ap constr.	feas. pts	number of eval.
solar1	30%	0.35%	96%	74%	3,792
solar2	0%	0%	97%	0%	1,635
solar3	0.49%	0%	99%	9%	30,525
solar4	0%	0%	83%	0%	44,303
solar5	0%	0%	83%	59%	3,405
solar6	90%	5%	99%	0%	3,539
solar7	2%	1%	74%	72%	2,224
solar8	1%	0.03%			
solar9	1%	0%			

there has been no violation of hidden constraints during the construction of this table

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**Optimization on solar1** 



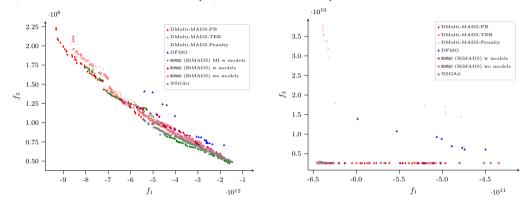
Instances

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# **Biobjective optimization (by L. Salomon)**



Pareto front approximations for solar8 (left) and solar9 (right) with different solvers with a budget of 5K evaluations. Taken from [Bigeon et al., 2022]

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Audet, C., Béchard, V., and Le Digabel, S. (2008). Nonsmooth optimization through Mesh Adaptive Direct Search and Variable Neighborhood Search. Journal of Global Optimization, 41(2):299-318. Bigeon, J., Le Digabel, S., and Salomon, L. (2022). Handling of constraints in multiobjective blackbox optimization. Technical Report G-2022-10, Les cahiers du GERAD. Le Digabel, S. and Wild, S. (2015). A Taxonomy of Constraints in Simulation-Based Optimization. Technical Report G-2015-57. Les cahiers du GERAD. Lemvre Garneau, M. (2015). Modelling of a solar thermal power plant for benchmarking blackbox optimization solvers. Master's thesis. Polytechnique Montréal.