

# solar: A solar thermal power plant simulator for blackbox optimization benchmarking

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# Presentation outline

**Introduction**

**The solar simulator**

**The solar instances**

**The solar features**

**Examples of results**

**References**

## Introduction

The solar simulator

The solar instances

The solar features

Examples of results

References

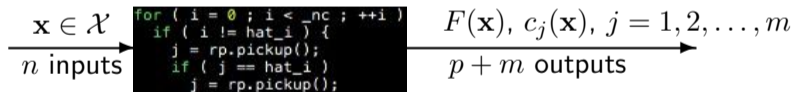
## Contributors

- ▶ This work is based on the MSc thesis of [Lemyre Garneau, 2015]
- ▶ The other contributors are
  - ▶ Charles Audet
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## Context: Blackbox Optimization (BBO)

$$\min_{\mathbf{x} \in \mathcal{X}} F(\mathbf{x}) \text{ s.t. } \mathbf{x} \in \Omega = \{\mathbf{x} \in \mathcal{X} : c_j(\mathbf{x}) \leq 0, j = 1, 2, \dots, m\}$$

$\mathcal{X}$  is a  $n$ -dimensional space,  $F$  can have  $p = 1$  or  $p = 2$  components, and the evaluations of  $F$  and the  $c_j$ 's are provided by a **blackbox**:



- ▶ Each call to the blackbox may be expensive
- ▶ The evaluation can fail
- ▶ Sometimes  $F(\mathbf{x}) \neq F(\mathbf{x})$
- ▶ Derivatives are not available and cannot be approximated

## Objectives of this work

Provide a realistic application for “true” BBO benchmarking, that

- ▶ is easy to install (stand-alone, standard code)
- ▶ is multiplatform
- ▶ allows to reproduce results
- ▶ includes many options allowing to
  - ▶ test different aspects of BBO such as
    - ▶ time-consuming evaluations
    - ▶ discrete/categorical variables
    - ▶ constraints handling
    - ▶ noise in the blackbox outputs
    - ▶ static surrogates
    - ▶ multiobjective optimization
  - ▶ propose sets of instances to draw performance/data profiles

## Introduction

## **The solar simulator**

## The solar instances

## The solar features

## Examples of results

## References

## CSP tower plant with molten salt thermal energy storage

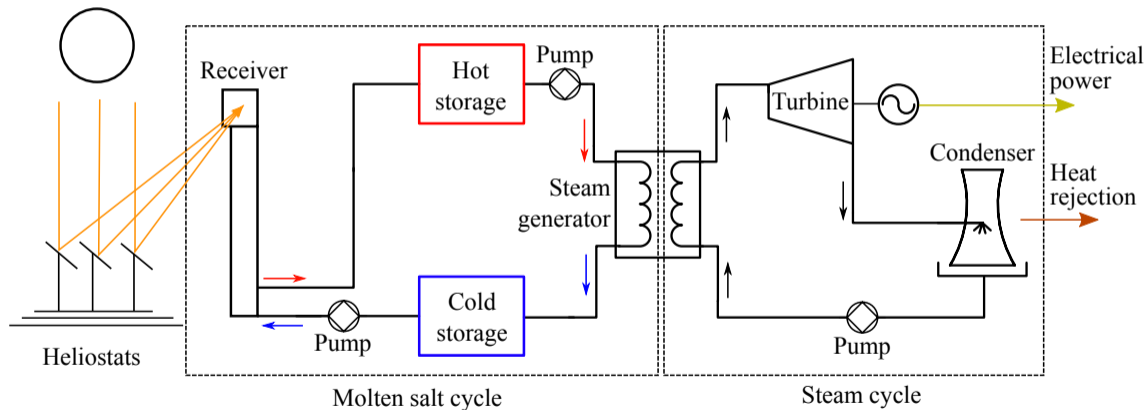
- ▶ A large number of mirrors (**heliostats**) reflects solar radiation on a receiver at the top of a tower
- ▶ The heat collected from the concentrated solar flux is removed from the receiver by a stream of molten salt
- ▶ Hot molten salt is then used to feed thermal power to a conventional power block
- ▶ The photo shows the Thémis CSP power plant, the first built with this design

Source: <https://commons.wikimedia.org/wiki/File:Themis-2.jpg>





## System dynamics



## Introduction

## The solar simulator

## **The solar instances**

## The solar features

## Examples of results

## References

## The solar code is

- ▶ a command-line application
- ▶ the “natural heir” of our **STYRENE** simulator [Audet et al., 2008]
- ▶ publicly available at <https://github.com/bbopt/solar> under the **GNU Lesser General Public License**
- ▶ a relatively simple code in standard C++ ( $\simeq 15$ k lines of codes)
- ▶ stand-alone: no external library to install
- ▶ multi-platform: C++ compiler is the only requirement

## Ten instances

Instance	# of variables		$n$	# of obj. $p$	# of constraints		$m$	# of stoch. outputs (obj. or constr.)	Static surrogate
	cont.	discr. (cat.)			simu.	a priori (lin.)			
solar1	8	1 (0)	9	1	2	3 (2)	5	1	no
solar2 <sup>1</sup>	12	2 (0)	14	1	9	4 (2)	13	3	yes
solar3	17	3 (1)	20	1	8	5 (3)	13	5	yes
solar4	22	7 (1)	29	1	9	7 (5)	16	6	yes
solar5	14	6 (1)	20	1	8	4 (3)	12	0	no
solar6	5	0 (0)	5	1	6	0 (0)	6	0	no
solar7	6	1 (0)	7	1	4	2 (1)	6	3	yes
solar8	11	2 (0)	13	2	4	5 (3)	9	3	yes
solar9	22	7 (1)	29	2	10	7 (5)	17	6	yes
solar10 <sup>2</sup>	5	0 (0)	5	1	0	0 (0)	0	0	yes

<sup>1</sup>analytic objective

<sup>2</sup>unconstrained

## Types of variables

$$\min_{\mathbf{x} \in \mathcal{X}} F(\mathbf{x}) \text{ s.t. } \mathbf{x} \in \Omega = \{\mathbf{x} \in \mathcal{X} : c_j(\mathbf{x}) \leq 0, j = 1, 2, \dots, m\}$$

- ▶ The  $n$  variables are described by the set  $\mathcal{X}$ . They can be continuous or discrete
- ▶  $\mathcal{X}$  includes bounds on most of the variables
- ▶ There are 29 possible variables. Each instance considers a subset of these variables. solar4 and solar9 consider all  $n = 29$  variables
- ▶ The solar6 and solar10 instances have no discrete variables. In these cases  $\mathcal{X} \subset \mathbb{R}^5$
- ▶ One of the discrete variable (the type of turbine) is categorical. solar considers it as an integer in  $\{1, 2, \dots, 8\}$

## Types of constraints

$$\min_{\mathbf{x} \in \mathcal{X}} F(\mathbf{x}) \text{ s.t. } \mathbf{x} \in \Omega = \{\mathbf{x} \in \mathcal{X} : c_j(\mathbf{x}) \leq 0, j = 1, 2, \dots, m\}$$

- ▶  $\mathcal{X}$  describes bounds on the variables and the discrete nature of some of the variables. These constraints are **unrelaxable**
- ▶ The  $m$  constraints in  $\Omega$  may be **a priori** or **simulation** constraints
- ▶ **A priori** constraints are also **unrelaxable**. In case of violation, the solar executable returns a flag to indicate a potential solver not to count the evaluation
- ▶ Most of the **a priori** constraints are **linear**
- ▶ **Simulation** constraints are **relaxable**
- ▶ Presence of **hidden** constraints
- ▶ All constraints (except the **hidden** ones) are **quantifiable**
  
- ▶ There are 18 possible constraints. Each instance considers a subset of these constraints, for a maximum of  $m = 17$  constraints in solar9

## Introduction

## The solar simulator

## The solar instances

## **The solar features**

## Examples of results

## References

## Getting started with solar

- ▶ Get the code at <https://github.com/bbopt/solar> and compile
- ▶ Command-line program that takes as arguments
  - ▶ a problem id (or instance number) in  $\{1, 2, \dots, 10\}$
  - ▶ the name of a file containing the coefficients of a point  $\mathbf{x}$and displays the values of  $F(\mathbf{x})$  and the  $c_j(\mathbf{x})$ 's
- ▶ Example: `> solar 7 x.txt` displays `f c1 c2 ... c6`  
(objective and six constraints)
- ▶ Simply executing `> solar` will guide the user and display the options, including a complete inline help with `> solar -help`



# Check the solar installation

```
> solar -check
```

Mac:

Core i9: 659s

M1 Pro: 451s

M1 Max: 444s

M2 Max: 393s

Windows:

Core i7: 2,684s

Linux:

AMD EPYC: 1,284s

```
[[12:34:11] [~/Desktop] > ./solar -check

Validation tests (can take several minutes):

    RNG test ( 1/ 2) ..... Ok      Time: CPU=8.8e-05      real=0
    RNG test ( 2/ 2) ..... Ok      Time: CPU=9e-06       real=0
    Eval test ( 1/26) ..... Ok      Time: CPU=0.090865    real=0
    Eval test ( 2/26) ..... Ok      Time: CPU=0.164074    real=0
    Eval test ( 3/26) ..... Ok      Time: CPU=8.55466     real=9
    Eval test ( 4/26) ..... Ok      Time: CPU=14.3939     real=14
    Eval test ( 5/26) ..... Ok      Time: CPU=12.444      real=12
    Eval test ( 6/26) ..... Ok      Time: CPU=1.67694     real=2
    Eval test ( 7/26) ..... Ok      Time: CPU=1.714       real=2
    Eval test ( 8/26) ..... Ok      Time: CPU=0.000297    real=0
    Eval test ( 9/26) ..... Ok      Time: CPU=1.8335      real=2
    Eval test (10/26) ..... Ok      Time: CPU=16.9975     real=17
    Eval test (11/26) ..... Ok      Time: CPU=0.088462    real=0
    Eval test (12/26) ..... Ok      Time: CPU=1.76882     real=2
    Eval test (13/26) ..... Ok      Time: CPU=2.03457     real=2
    Eval test (14/26) ..... Ok      Time: CPU=57.289      real=57
    Eval test (15/26) ..... Ok      Time: CPU=76.4028     real=76
    Eval test (16/26) ..... Ok      Time: CPU=2.17247     real=2
    Eval test (17/26) ..... Ok      Time: CPU=50.1873     real=51
    Eval test (18/26) ..... Ok      Time: CPU=50.3843     real=50
    Eval test (19/26) ..... Ok      Time: CPU=50.3955     real=50
    Eval test (20/26) ..... Ok      Time: CPU=3.31858     real=4
    Eval test (21/26) ..... Ok      Time: CPU=3.21749     real=3
    Eval test (22/26) ..... Ok      Time: CPU=5.77947     real=6
    Eval test (23/26) ..... Ok      Time: CPU=0.003279    real=0
    Eval test (24/26) ..... Ok      Time: CPU=3.86108     real=4
    Eval test (25/26) ..... Ok      Time: CPU=2.24941     real=2
    Eval test (26/26) ..... Ok      Time: CPU=25.7252     real=26

This version of SOLAR is valid

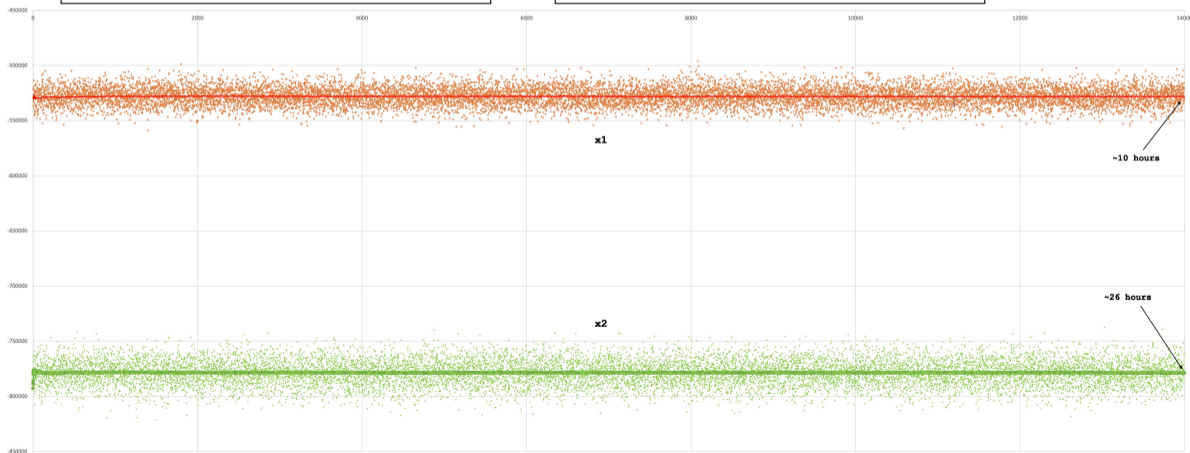
CPU time : 392.748s
Real time: 393s
```

## Stochasticity and replications

- ▶ Stochasticity is due to the Monte Carlo simulation for the heliostats field
- ▶ Random seed is set to the same value by default: This corresponds to a deterministic blackbox
- ▶ Use the option `-seed` to change the random seed
- ▶ The option `-seed=diff` makes the blackbox stochastic
- ▶ The option `-rep` executes several simulations and outputs average values
- ▶ A high number of replications will tend to decrease stochasticity but will lead to expensive evaluations (which is great in BBO benchmarking)

## Illustration of replications for the objective of solar1

```
> solar 1 -rep=14000 x1.txt and > solar 1 -rep=14000 x2.txt
```



## Multi-fidelity

- ▶ The option `-fid` with a value in  $]0; 1]$  changes the fidelity of the simulator
- ▶ Each different value of this option generates a **static surrogate**
- ▶ `-fid=1` corresponds to the “true” blackbox (called the **truth**)
- ▶ This option allows to consider **multi-fidelity metamodels** or **variable precision static surrogates**
- ▶ Note that using the `-rep` option also allows to consider such surrogates when the truth is considered to be obtained with high number of replications

## Introduction

## The solar simulator

## The solar instances

## The solar features

## **Examples of results**

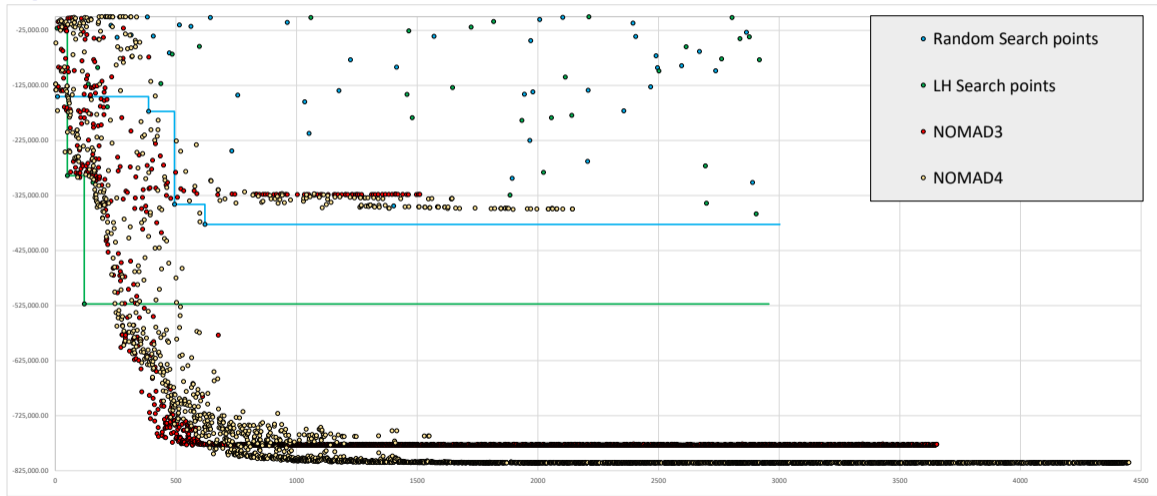
## References

## Feasibility with sampling and NOMAD

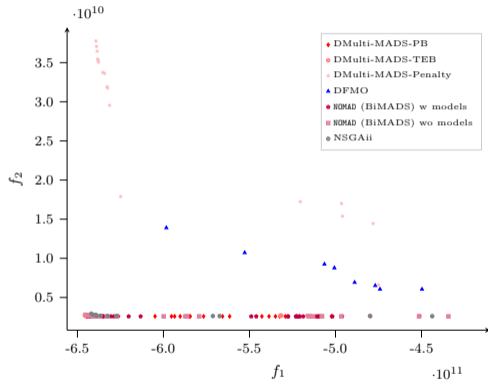
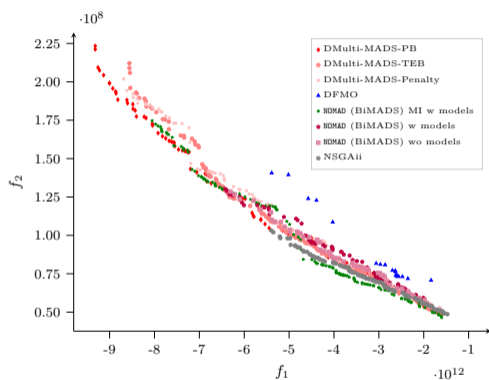
Instance	LH search (10k points)			NOMAD3			
	satisf. <b>ap</b>	constr.	feas. pts	satisf. <b>ap</b>	constr.	feas. pts	number of eval.
solar1	30%		0.35%	96%		74%	3,792
solar2	0%		0%	97%		0%	1,635
solar3	0.49%		0%	99%		9%	30,525
solar4	0%		0%	83%		0%	44,303
solar5	0%		0%	83%		59%	3,405
solar6	90%		5%	99%		0%	3,539
solar7	2%		1%	74%		72%	2,224
solar8	1%		0.03%				
solar9	1%		0%				

there has been no violation of **hidden** constraints during the construction of this table

# Optimization on solar1



## Biobjective optimization (by L. Salomon)



Pareto front approximations for solar8 (left) and solar9 (right) with different solvers with a budget of 5K evaluations. Taken from [Bigeon et al., 2022]



## Introduction

## The solar simulator

## The solar instances

## The solar features

## Examples of results

## References

# References I

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