

Order-Based Error for Managing Ensembles of Surrogates in Derivative-Free Optimization

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Presentation outline

Blackbox optimization

The MADS algorithm

Surrogate-assisted optimization

Order error and ensemble of models

Computational results

Discussion

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Blackbox optimization (BBO) problems

- ▶ Optimization problem:

$$\min_{x \in \Omega} f(x)$$

- ▶ $\Omega = \{x \in \mathcal{X} : c_j(x) \leq 0, j \in \{1, 2, \dots, m\}\} \subseteq \mathbb{R}^n$.
- ▶ \mathcal{X} : Bounds and/or nonquantifiable constraints.
- ▶ Evaluations of f (the **objective function**) and of the functions defining Ω are usually the result of a computer code (a **blackbox**).

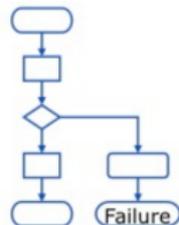
Blackboxes as illustrated by J. Simonis [ISMP 2009]



Long runtime



Large memory
requirement



Software
might fail



No derivatives
available



Local
optima



Non-smooth,
noisy

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Mesh Adaptive Direct Search (MADS)

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- ▶ Iterative algorithm that evaluates the blackbox at some **trial points** on a spatial discretization called the **mesh**.
- ▶ One iteration = **search** and **poll**.

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- ▶ The search allows trial points generated anywhere on the mesh.
- ▶ The poll consists in generating a list of trial points constructed from **poll directions**. These directions grow dense.

Mesh Adaptive Direct Search (MADS)

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- ▶ The search allows trial points generated anywhere on the mesh.
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- ▶ At the end of the iteration, the mesh size is reduced if no new success point is found.

[0] Initializations (x_0, Δ_0 : initial poll size)

[1] Iteration k

let $\delta^k \leq \Delta^k$ be the mesh size parameter

Search

test a finite number of mesh points

Poll (if the Search failed)

construct set of directions D_k

test poll set $P_k = \{x_k + \delta^k d : d \in D_k\}$

with $\|\delta^k d\| \simeq \Delta_k$

[2] Updates

if success

$x_{k+1} \leftarrow$ success point

increase Δ^k

else

$x_{k+1} \leftarrow x_k$

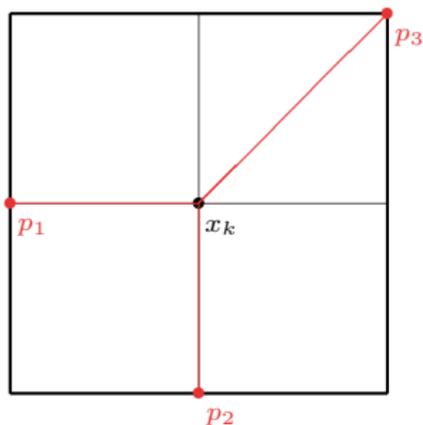
decrease Δ^k

$k \leftarrow k + 1$, stop if $\Delta^k \leq \Delta_{\min}$ or go to **[1]**

Poll illustration (successive fails and mesh shrinks)

$$\delta^k = 1$$

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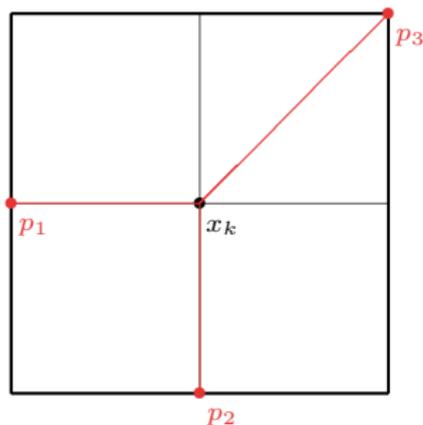


trial points = $\{p_1, p_2, p_3\}$

Poll illustration (successive fails and mesh shrinks)

$$\delta^k = 1$$

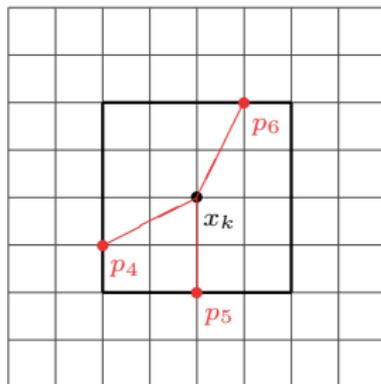
$$\Delta^k = 1$$



trial points = $\{p_1, p_2, p_3\}$

$$\delta^{k+1} = 1/4$$

$$\Delta^{k+1} = 1/2$$

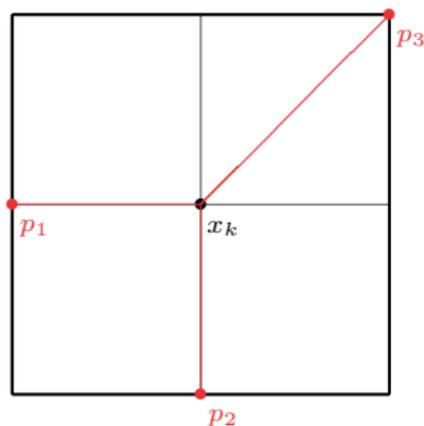


= $\{p_4, p_5, p_6\}$

Poll illustration (successive fails and mesh shrinks)

$$\delta^k = 1$$

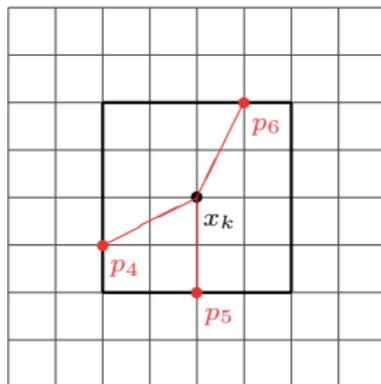
$$\Delta^k = 1$$



trial points = $\{p_1, p_2, p_3\}$

$$\delta^{k+1} = 1/4$$

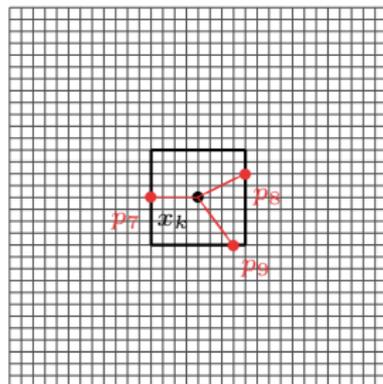
$$\Delta^{k+1} = 1/2$$



trial points = $\{p_4, p_5, p_6\}$

$$\delta^{k+2} = 1/16$$

$$\Delta^{k+2} = 1/4$$



trial points = $\{p_7, p_8, p_9\}$

Blackbox optimization

The MADS algorithm

Surrogate-assisted optimization

Order error and ensemble of models

Computational results

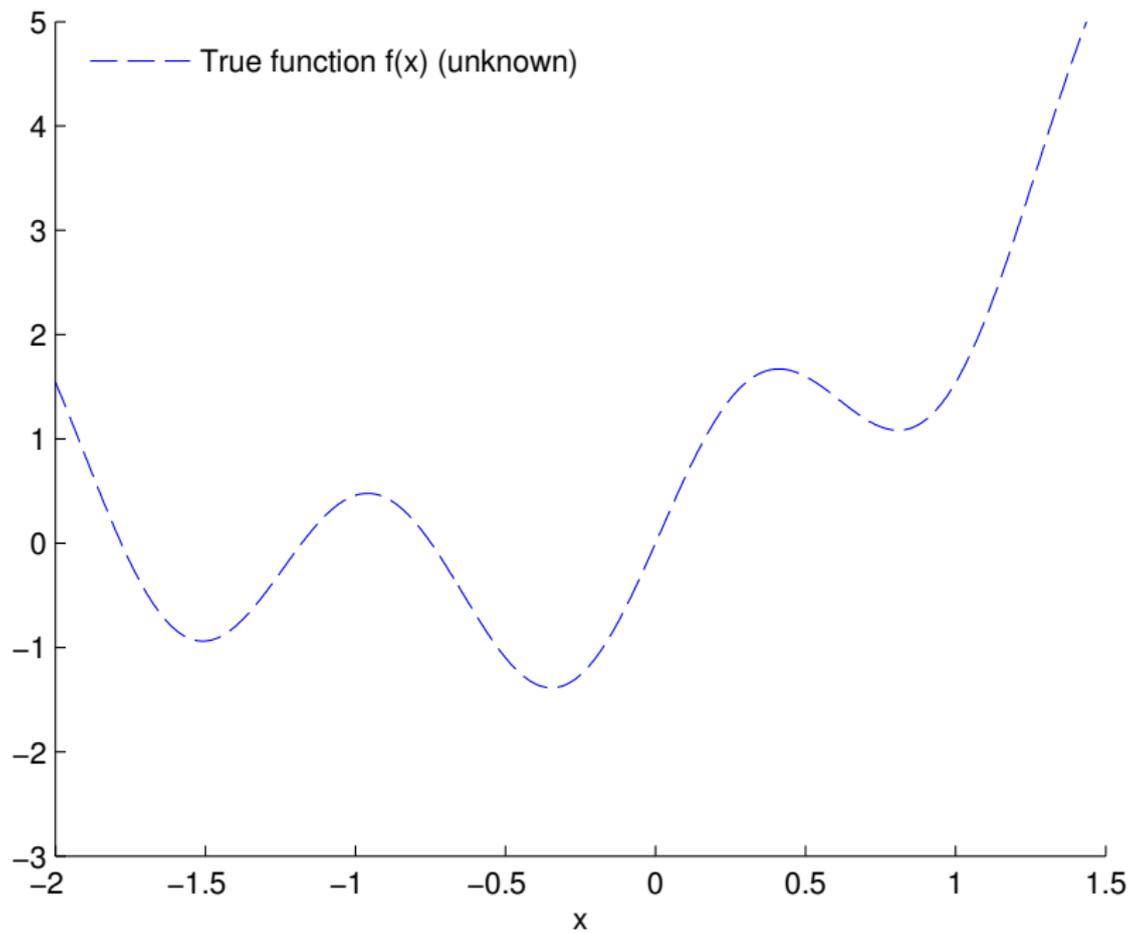
Discussion

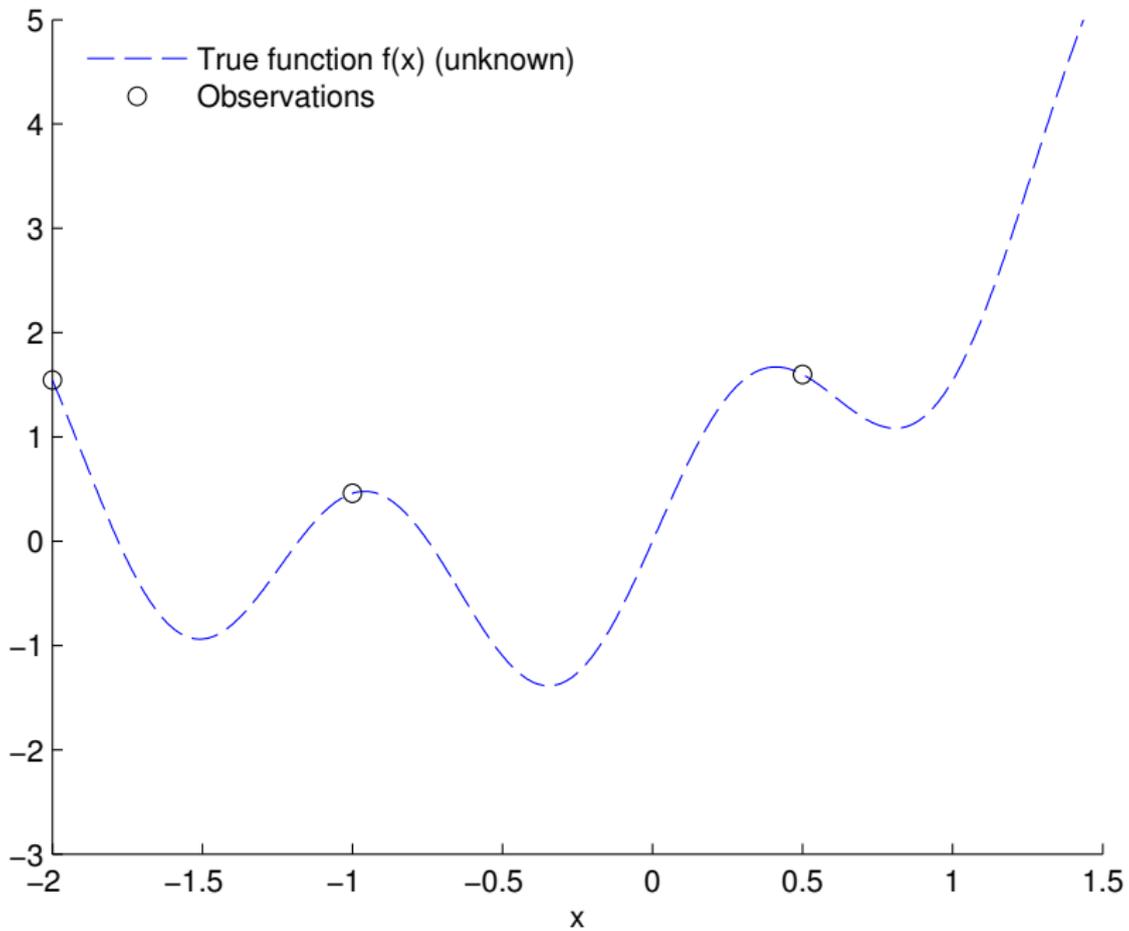
Surrogate-assisted optimization

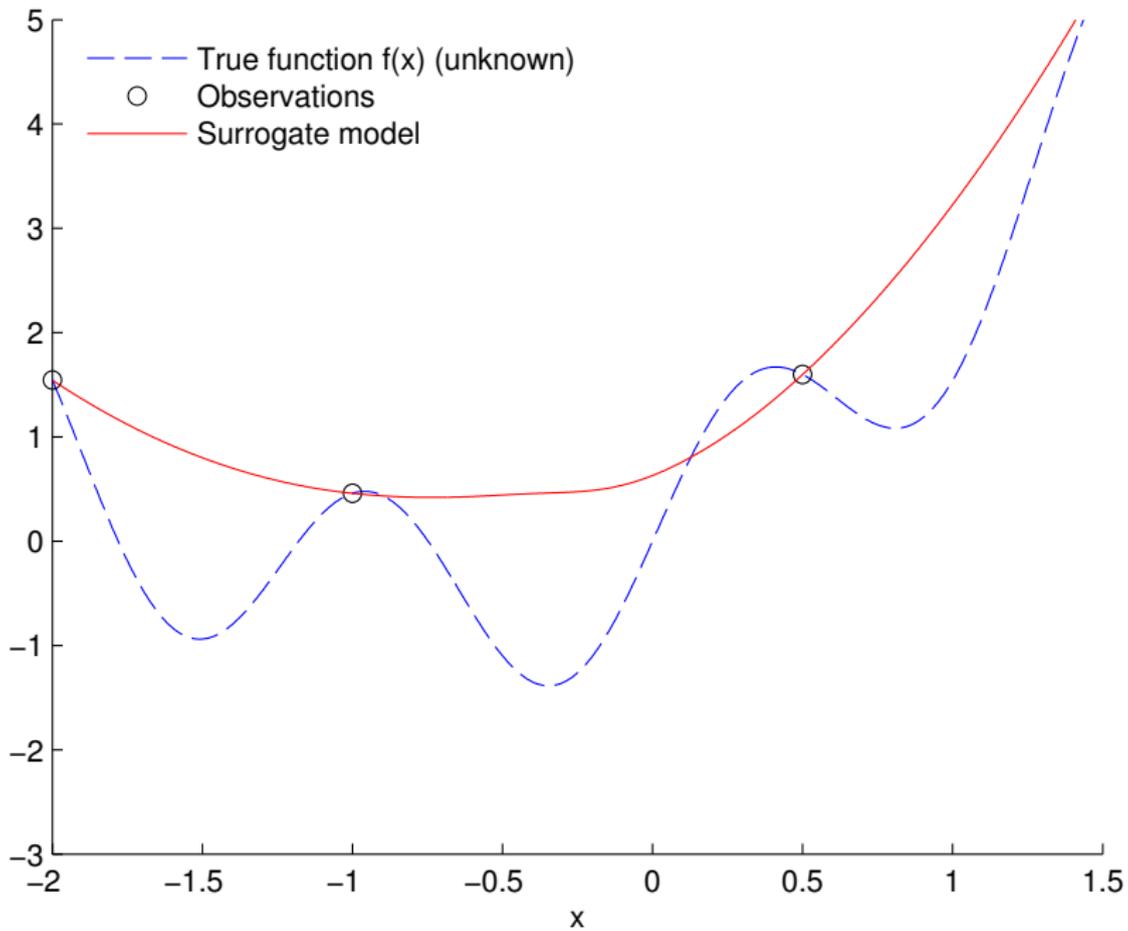
1. Use $[\mathbf{X}, f(\mathbf{X})]$ to build a surrogate \hat{f} of the function f .
2. Find $\mathbf{x}_S \in \underset{\mathbf{x}}{\operatorname{argmin}} \hat{f}(\mathbf{x})$.
3. Evaluate $f(\mathbf{x}_S)$.
4. $\mathbf{X} \leftarrow \mathbf{X} \cup \mathbf{x}_S$.
5. Go back to [Step 1](#).

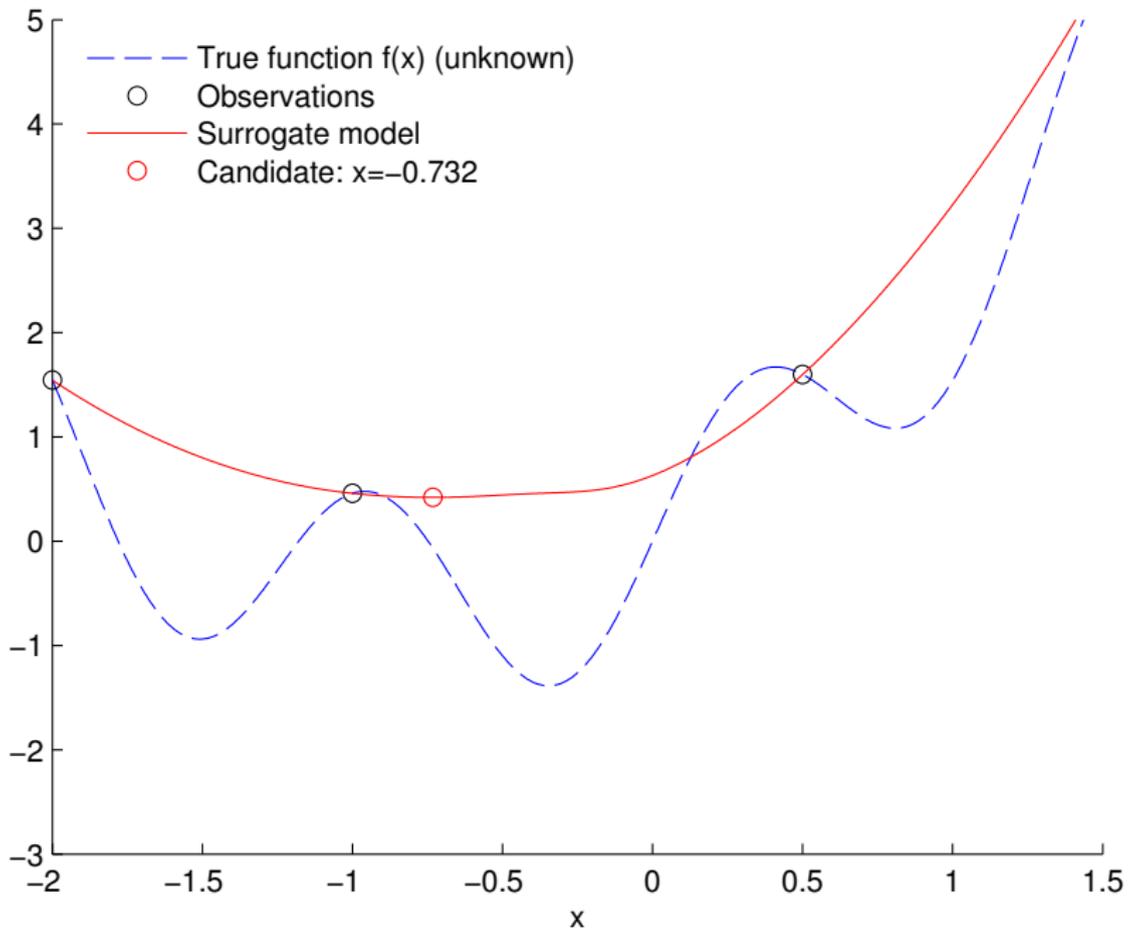
For constrained problems the same method can be used for constrained problems:

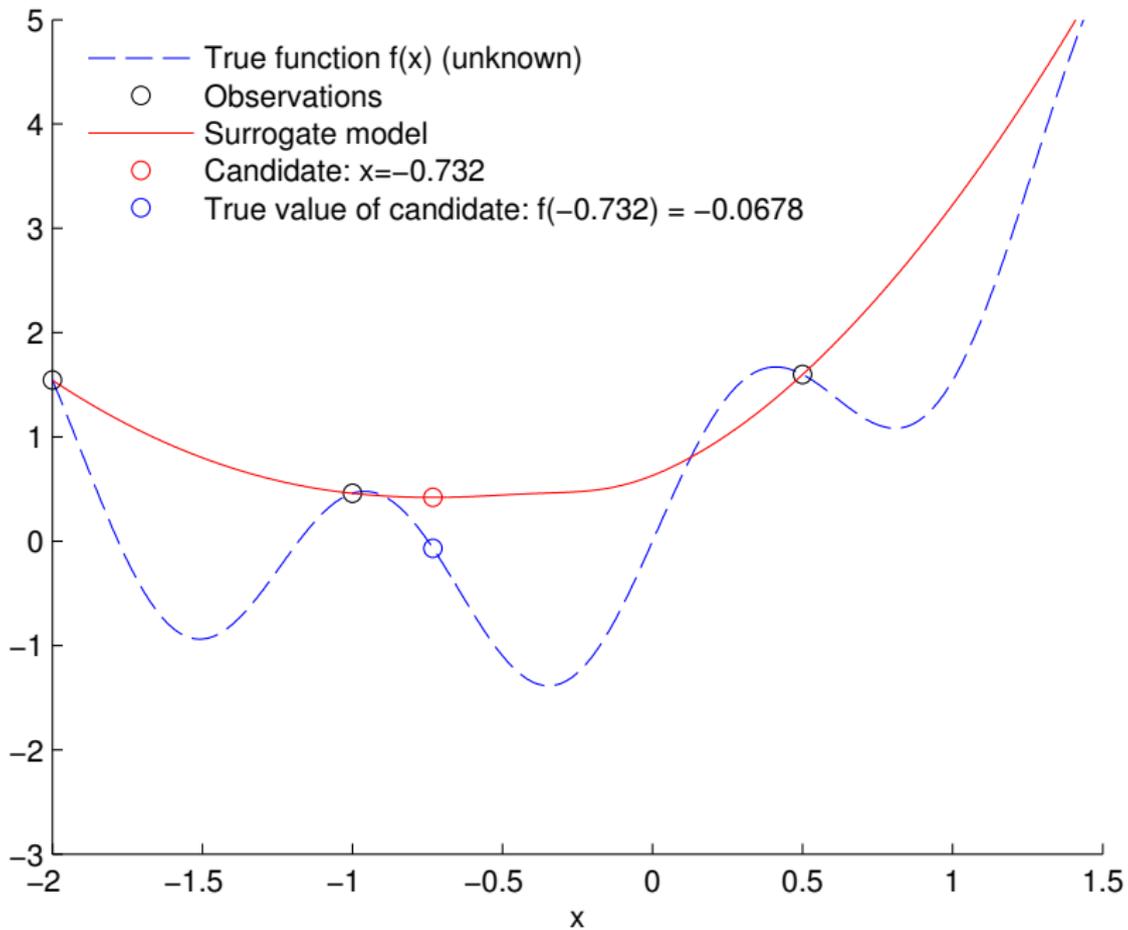
- ▶ Build the models of the constraints.
- ▶ $\mathbf{x}_S \leftarrow$ minimizer of \hat{f} subject to the constraints $\hat{c}_j \leq 0$, $j = 1, 2, \dots, m$.

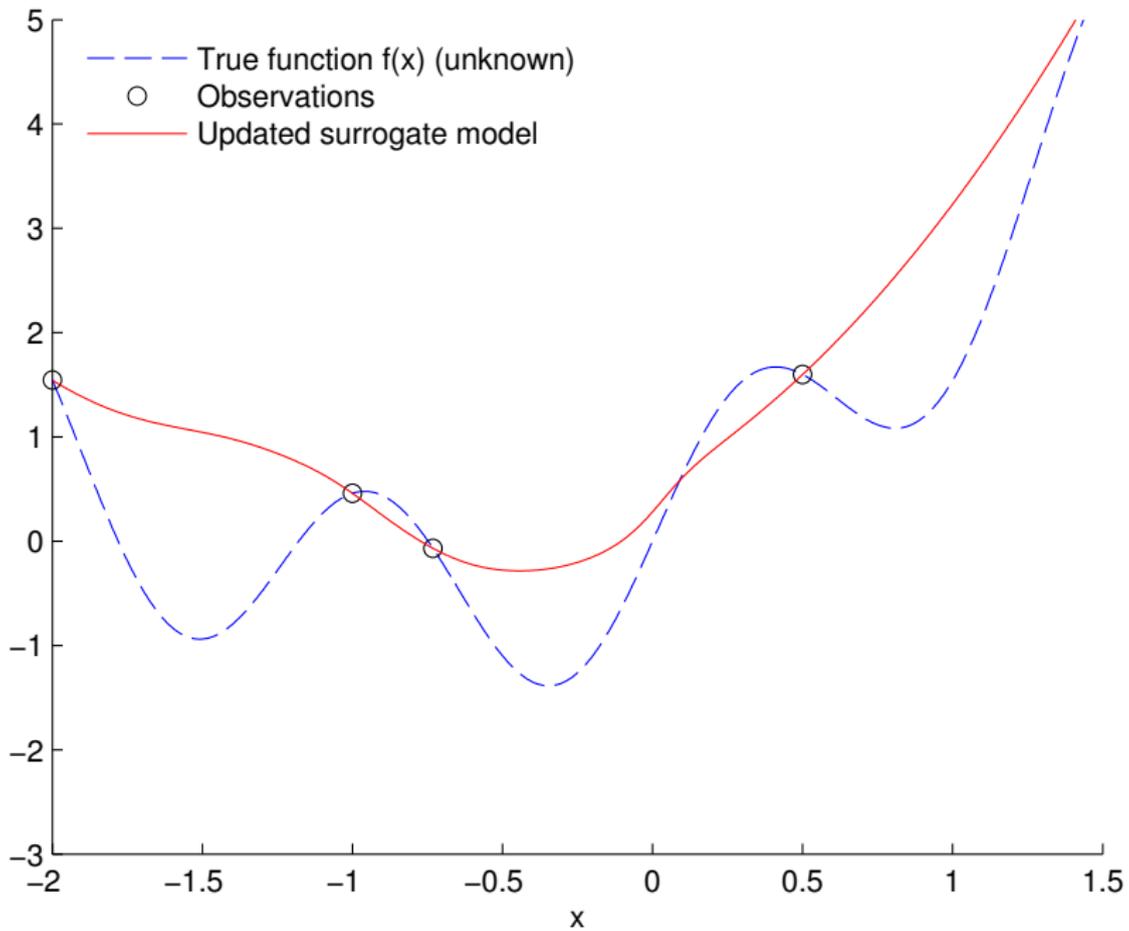


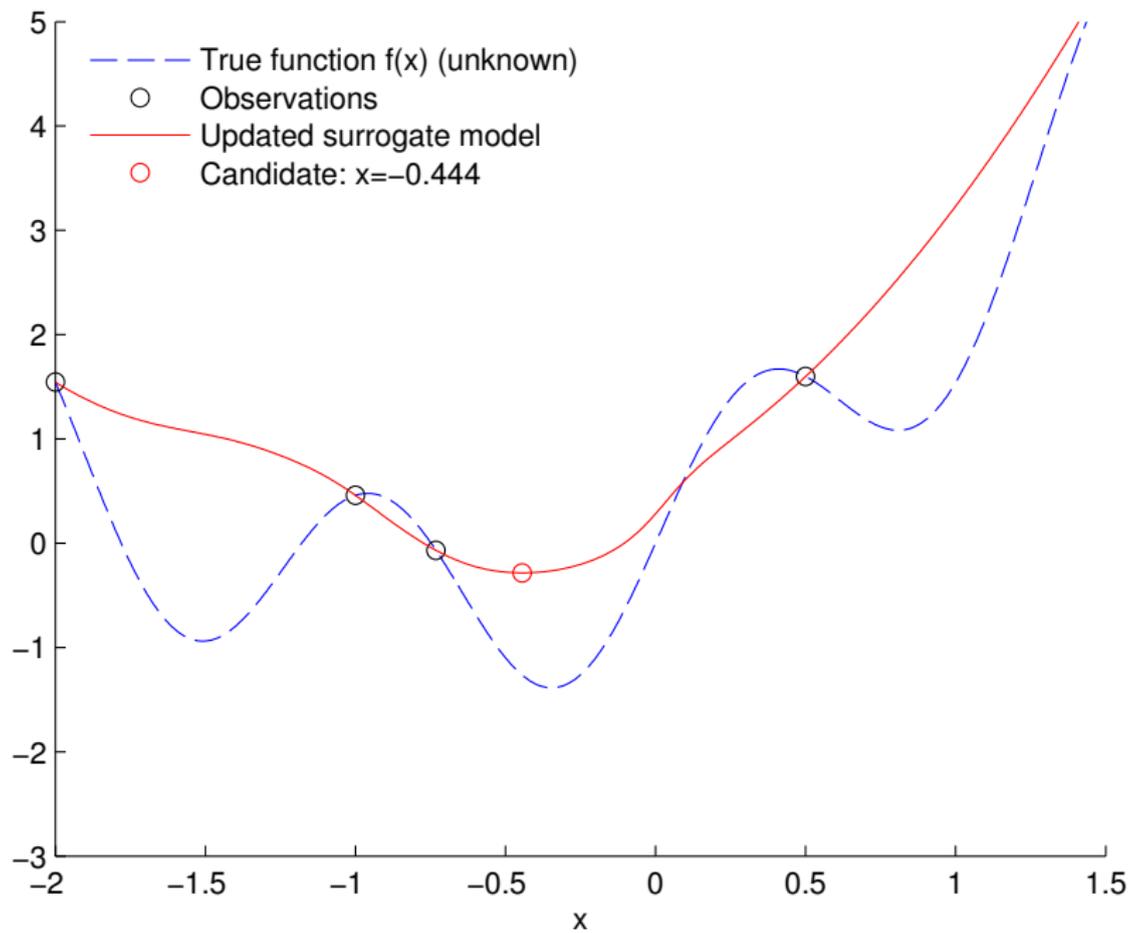


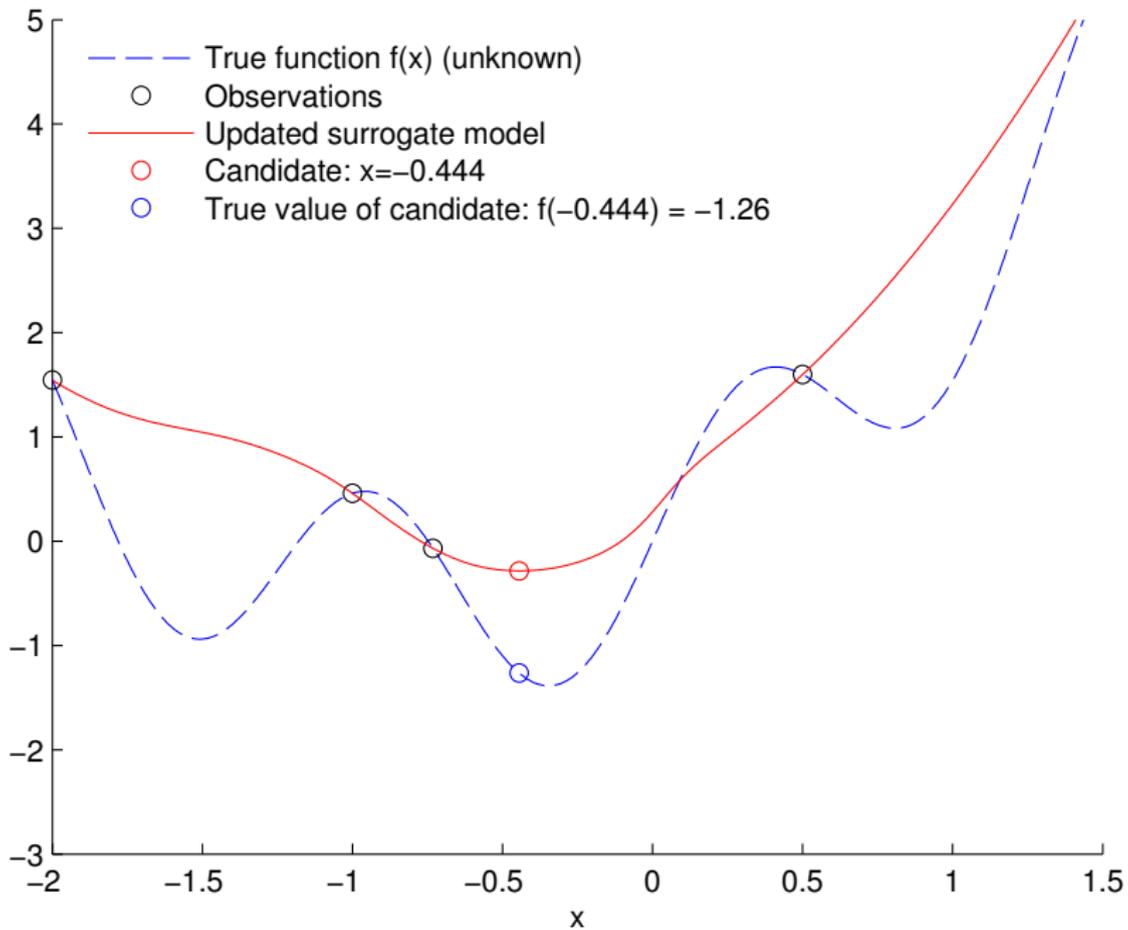


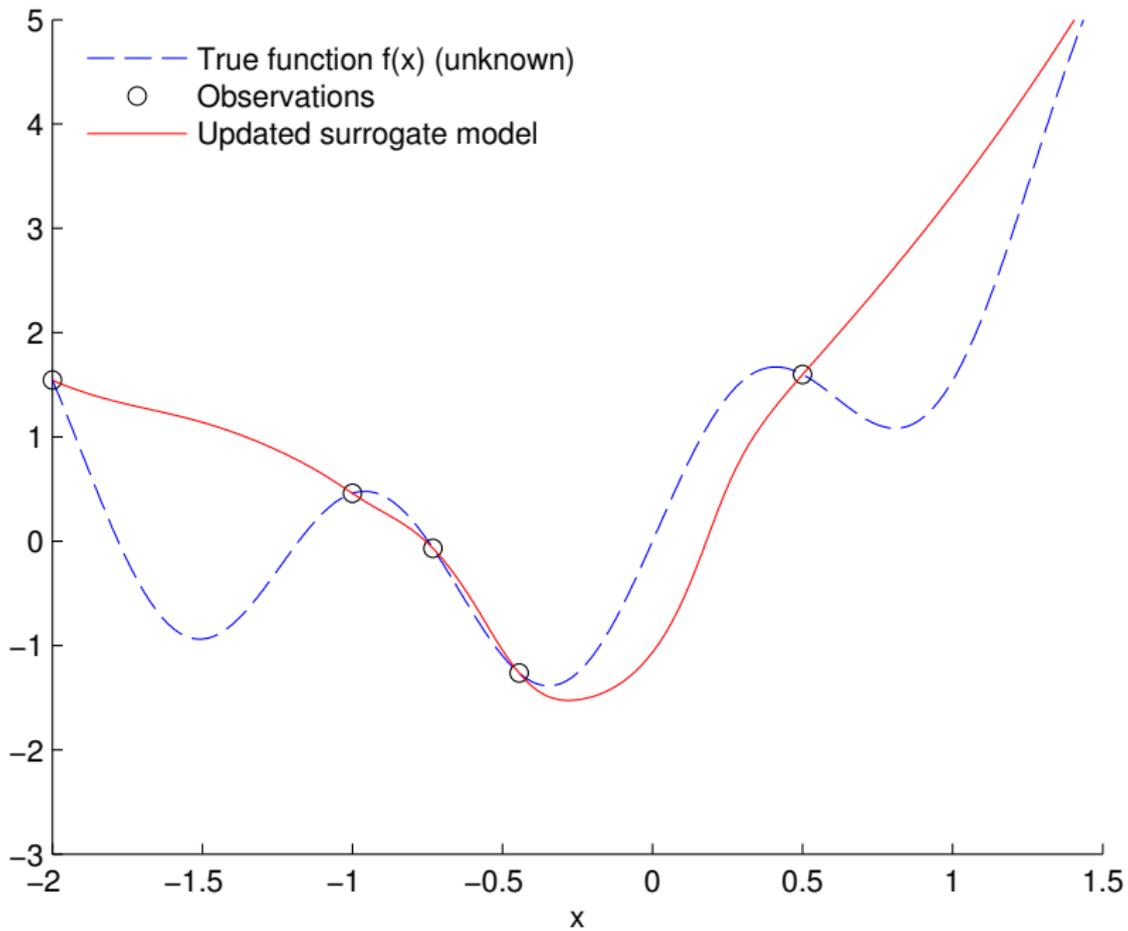


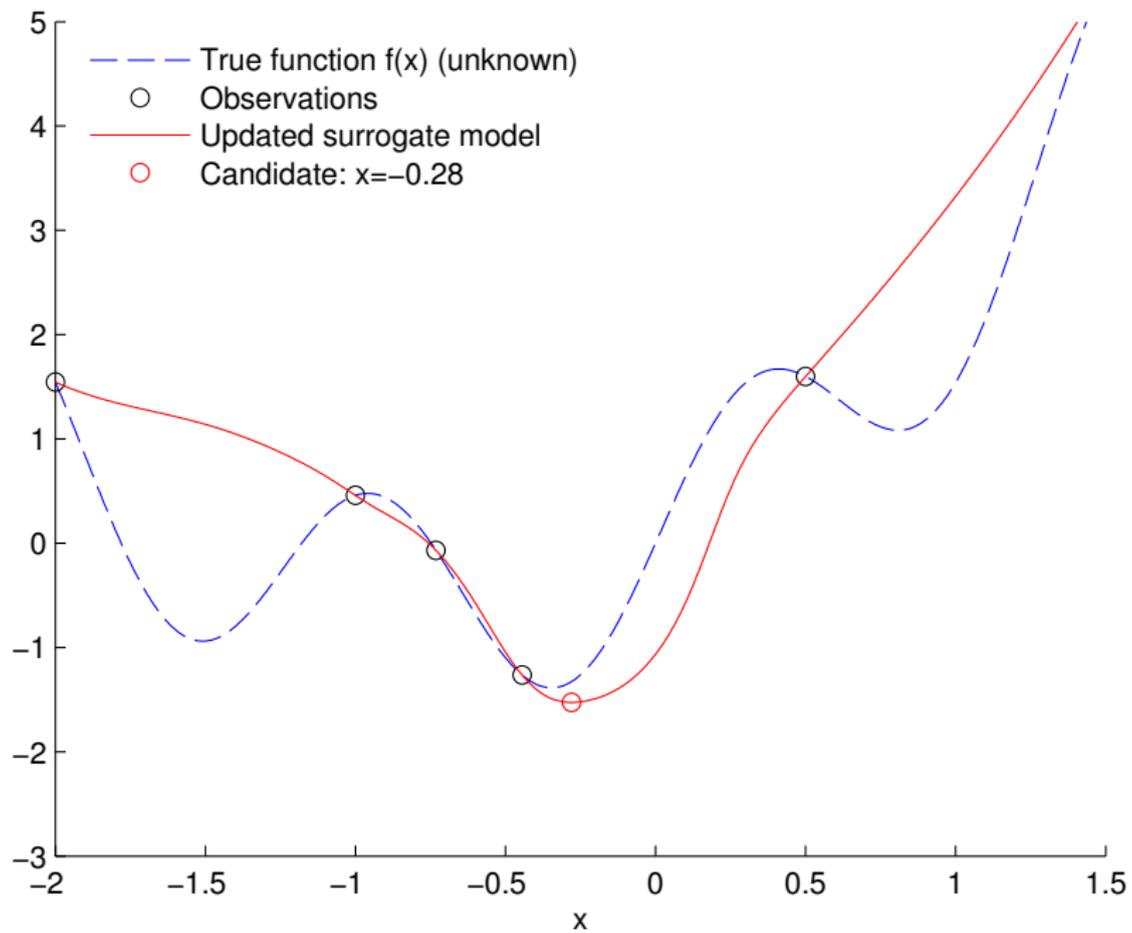


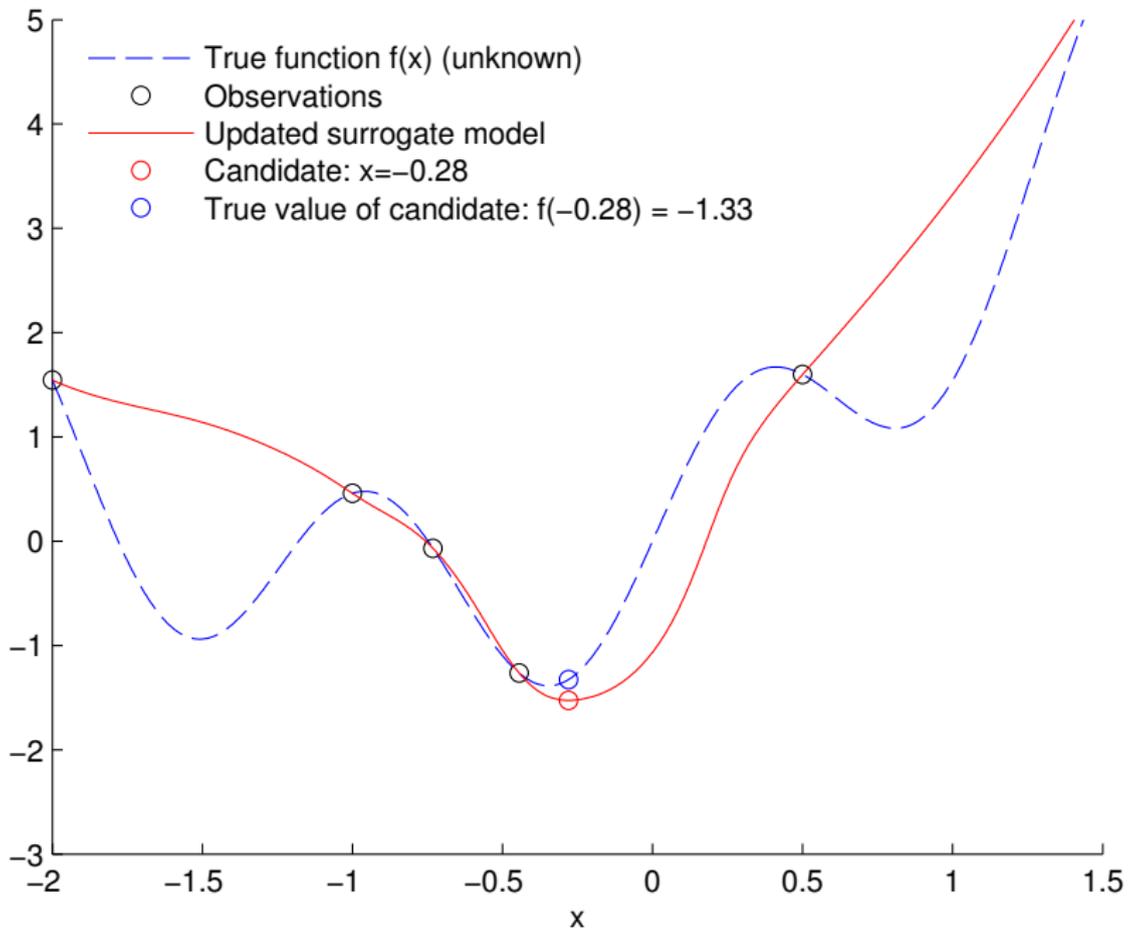


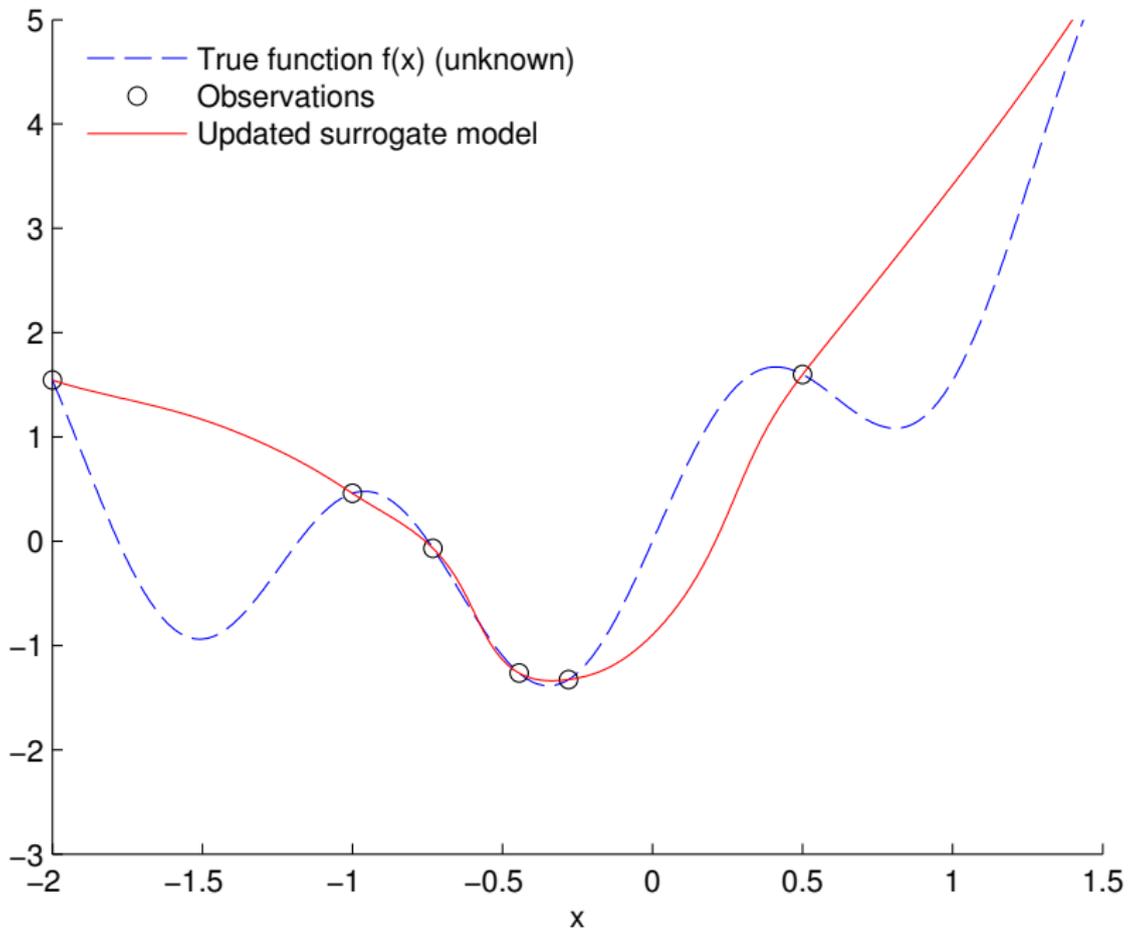


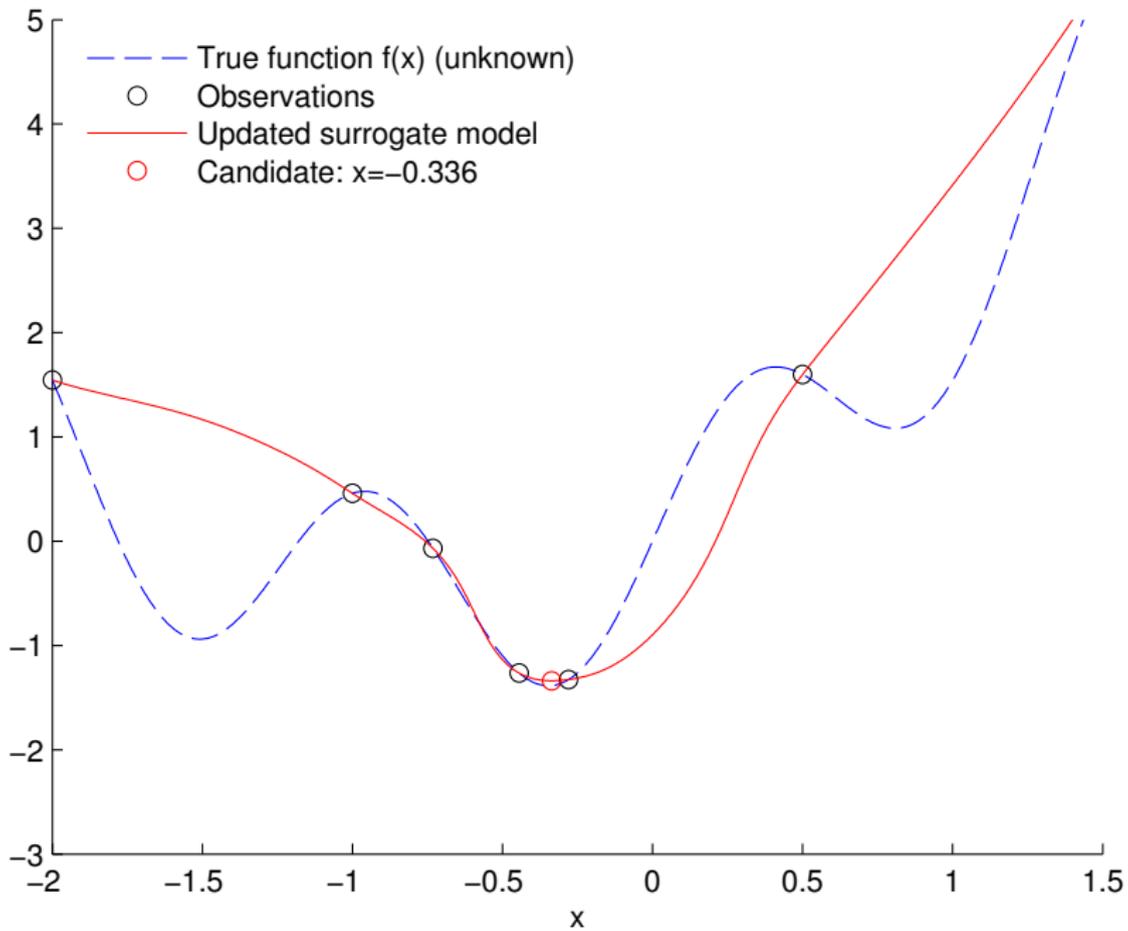


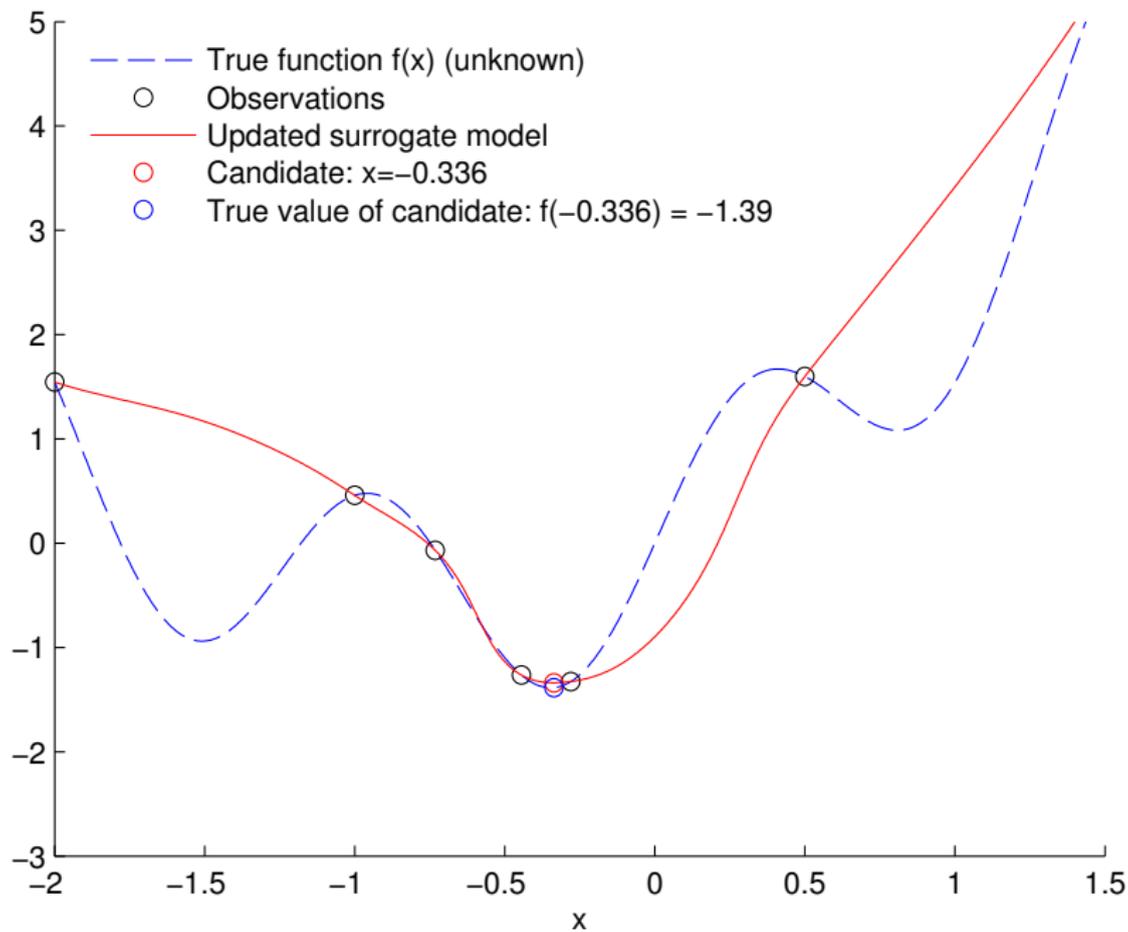


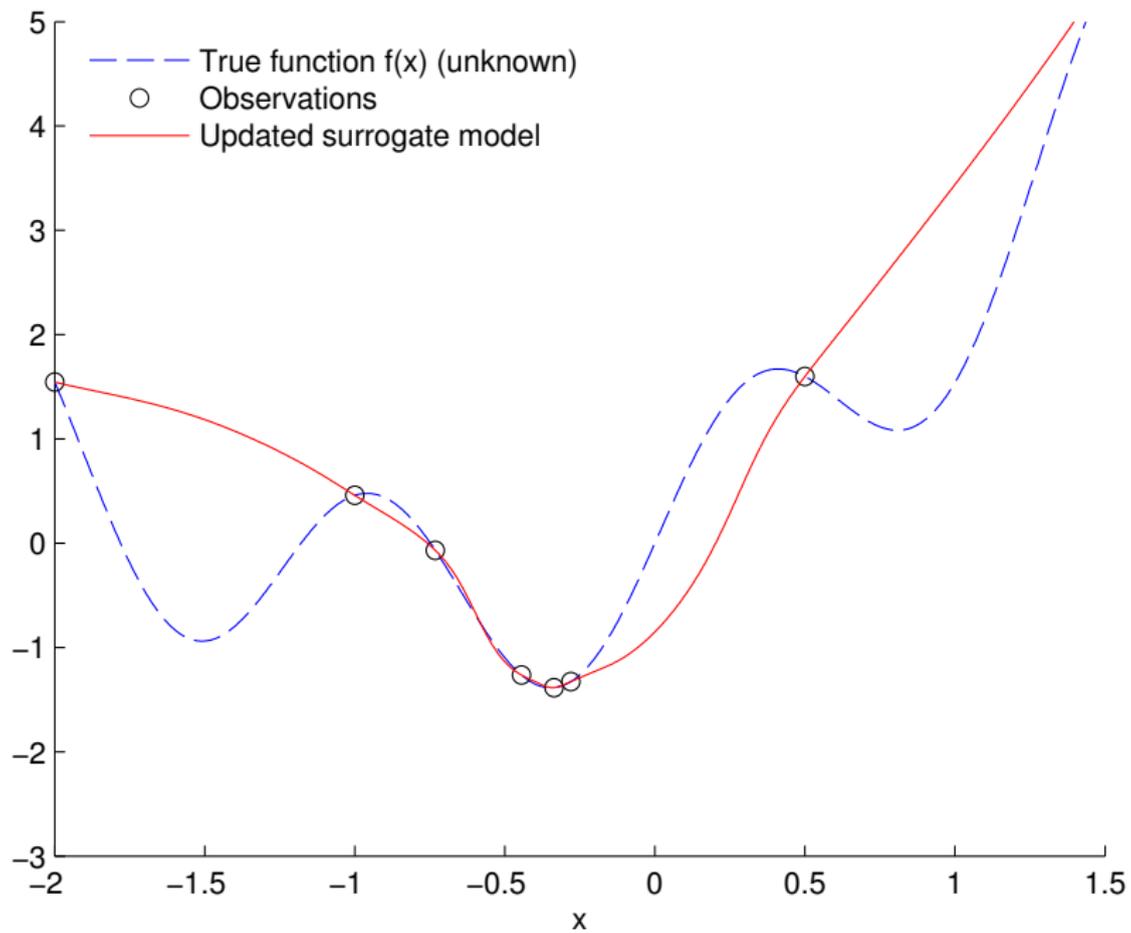


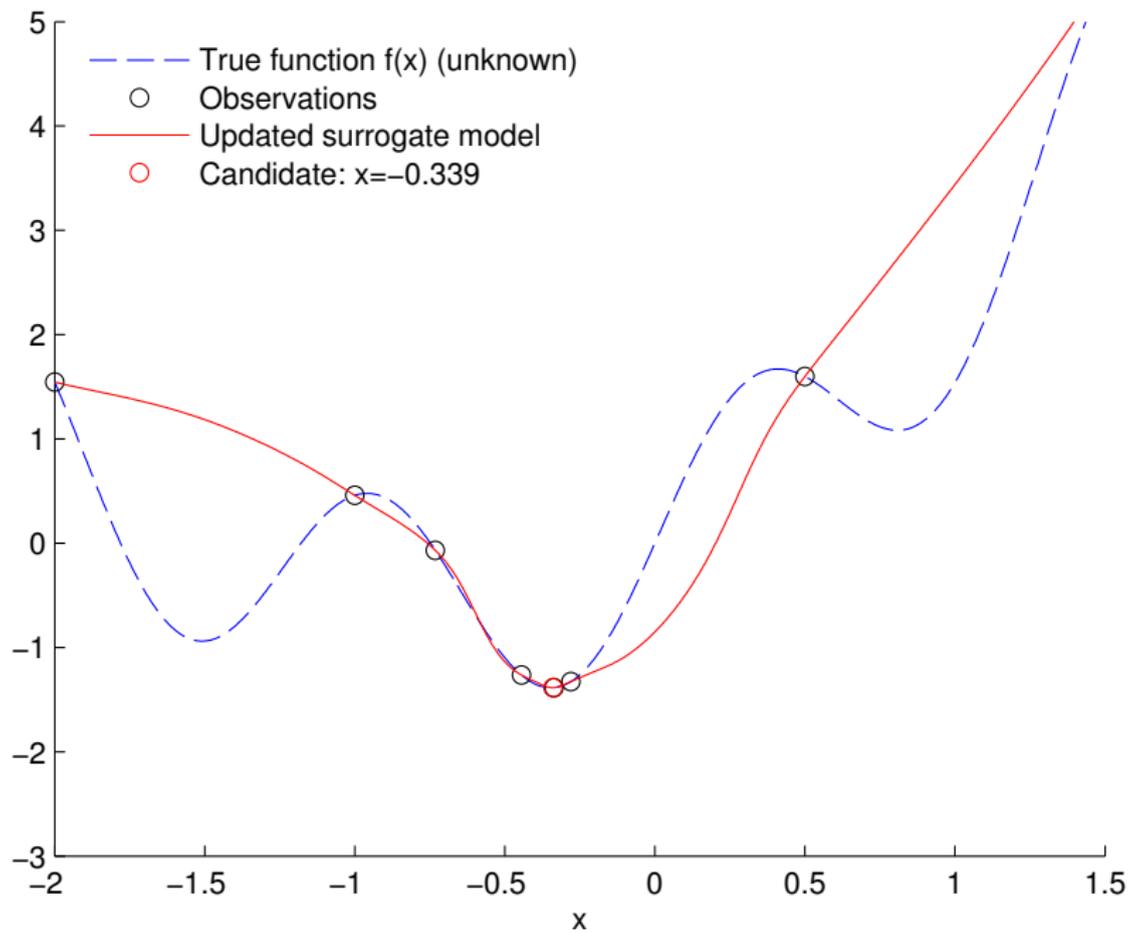












Surrogate-assisted optimization in MADS

1. Initialization:

- ▶ Initial design (x_0).
- ▶ Initial mesh and poll sizes (δ_0, Δ_0).

2. Search

- ▶ Build the surrogate models \hat{f} and $\{\hat{c}_j\}_{j=1,2,\dots,m}$.
- ▶ $\mathbf{x}_S \leftarrow$ solution of the surrogate problem, projected on the current mesh.
- ▶ If \mathbf{x}_S is a success, repeat the search.

3. Poll

- ▶ Construct the poll candidates.
- ▶ Use the surrogate models to order the poll candidates.
- ▶ Evaluate the poll candidates **opportunistically**.

4. If no stopping criteria is met, go back to [Step 2](#).

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Surrogate modeling techniques

- ▶ **Polynomial response surface (PRS):**

$$\hat{y}(\mathbf{x}) = \sum_{j=1}^q \alpha_j h_j(\mathbf{x}) \quad \text{where } h_j(\mathbf{x}) \text{ is a polynomial of } \mathbf{x}$$

- ▶ **Radial basis function (RBF):**

$$\hat{y}(\mathbf{x}) = \sum_{j=1}^p \alpha_j \phi(\|\mathbf{x} - \mathbf{x}_j\|_2) \quad \text{where } \phi(d) = \exp\left(-\frac{r_\phi^2 d^2}{d_{mean}^2}\right)$$

- ▶ **Kernel smoothing (KS):**

$$\hat{y}(\mathbf{x}) = \frac{\sum_{i=1}^p \phi(\|\mathbf{x} - \mathbf{x}_i\|_2) y(\mathbf{x}_i)}{\sum_{i=1}^p \phi(\|\mathbf{x} - \mathbf{x}_i\|_2)}$$

Ensemble of models

For each blackbox output (i.e. the objective and each constraint):

- ▶ Build an ensemble of surrogate models (Several PRS, RBF, KS, with various parameters).
- ▶ Compute the error for each model.
- ▶ Select the best model.

→ **Which error metric to use?** *(we will compare two candidates)*

Quadratic error

Root Mean Square Error (RMSE):

$$\mathcal{E}_{RMSE} = \sqrt{\frac{1}{p} \sum_{i=1}^p \left(y(\mathbf{x}_i) - \hat{y}(\mathbf{x}_i) \right)^2}$$

→ Quantifies the error on the training points but not the predictive accuracy outside of the training points.

Leave-one-out cross-validation

For each $\mathbf{x}_i \in \mathbf{X}$, build the model $\hat{y}^{(-i)}$ by leaving out the observation $[\mathbf{x}_i, y(\mathbf{x}_i)]$.

PRESS (Predicted RESidual Sum of Squares): **Method 1/2:**

$$\mathcal{E}_{PRESS} = \sqrt{\frac{1}{p} \sum_{i=1}^p \left(y(\mathbf{x}_i) - \hat{y}^{(-i)}(\mathbf{x}_i) \right)^2}$$

→ Quantifies the predictive accuracy, but is the model really suited for surrogate-assisted optimization?

What is a good model for surrogate-assisted optimization

- ▶ Good model of the objective f : respects the **order** between two candidates:

$$f(\mathbf{x}) \leq f(\mathbf{x}') \Leftrightarrow \hat{f}(\mathbf{x}) \leq \hat{f}(\mathbf{x}') \text{ for all } \mathbf{x}, \mathbf{x}' \in \mathcal{X} .$$

- ▶ Good model of a constraint c_j : respects the **sign** of the function:

$$c_j(\mathbf{x}) \leq 0 \Leftrightarrow \hat{c}_j(\mathbf{x}) \leq 0 \text{ for all } \mathbf{x} \in \mathcal{X} .$$

Order error

Idea: quantify the violation of those two conditions

$$f(\mathbf{x}) \leq f(\mathbf{x}') \Leftrightarrow \hat{f}(\mathbf{x}) \leq \hat{f}(\mathbf{x}') \text{ for all } \mathbf{x}, \mathbf{x}' \in \mathcal{X}$$

$$c_j(\mathbf{x}) \leq 0 \Leftrightarrow \hat{c}_j(\mathbf{x}) \leq 0 \text{ for all } \mathbf{x} \in \mathcal{X} .$$

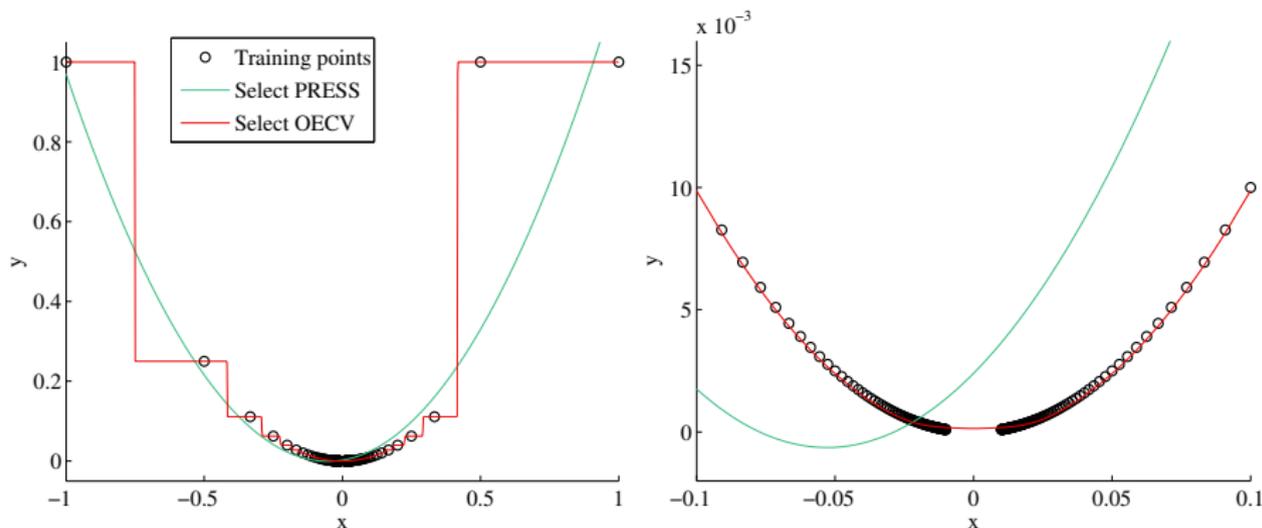
OECV (Order Error with Cross-Validation): **Method 2/2:**

$$\mathcal{E}_{OECV} = \begin{cases} \frac{1}{p^2} \sum_{i,j=1}^p \theta\left(f(\mathbf{x}_i) - f(\mathbf{x}_j), \hat{f}^{(-i)}(\mathbf{x}_i) - \hat{f}^{(-j)}(\mathbf{x}_j)\right) & \text{for the objective function} \\ \frac{1}{p} \sum_{i=1}^p \theta\left(c(\mathbf{x}_i), \hat{c}^{(-i)}(\mathbf{x}_i)\right) & \text{for a constraint function} \end{cases}$$

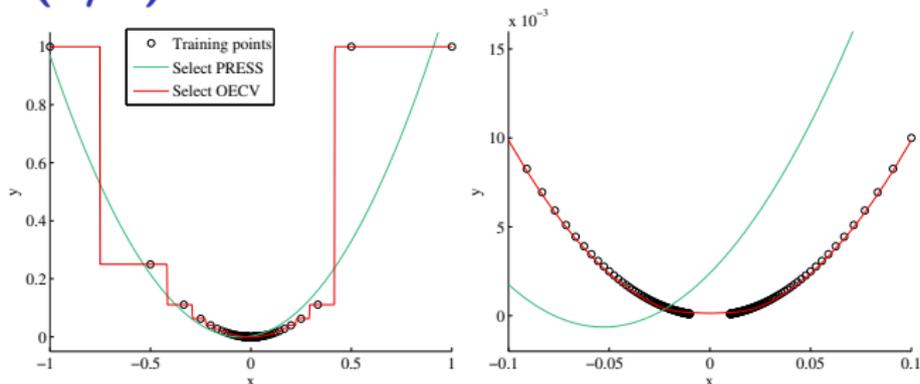
where $\theta(a, b) = (a \leq 0) \text{ XOR } (b \leq 0)$.

Example (1/2)

$$\mathbf{X} = \{\pm 1/k, k = 1, 2, \dots, 100\} \quad \text{and} \quad y(x) = \begin{cases} x^2 & \text{if } x \leq 1/2 \\ 1 & \text{otherwise.} \end{cases}$$



Example (2/2)



- ▶ PRESS: Quadratic regression. OECV: KS with $r_\phi = 10$.
- ▶ Left figure: Quadratic regression is doing fine in general while KS looks weird.
- ▶ Right figure (zoom): KS optimizer is better.
- ▶ PRESS favors models that are generally good while OECV is more adapted to surrogate based optimization.

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Computational results

- ▶ Tests on two real applications from aeronautics.
- ▶ Compared methods:

Quad		MADS with local quadratic model search
Select PRESS		MADS with Ensemble of surrogates & PRESS
Select OECV		MADS with Ensemble of surrogates & OECV

Test problem 1: MDO Simplified wing

Min: Wind drag

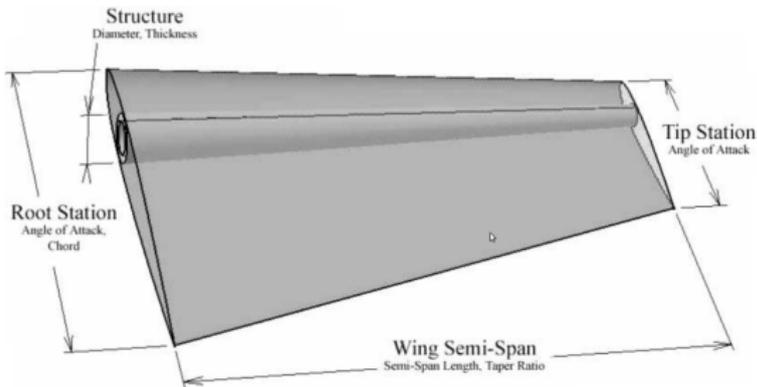
st: Shear stress $\leq 73,200$ psi

Tensile stress $\leq 47,900$ psi

Sum of the weights \leq total lift

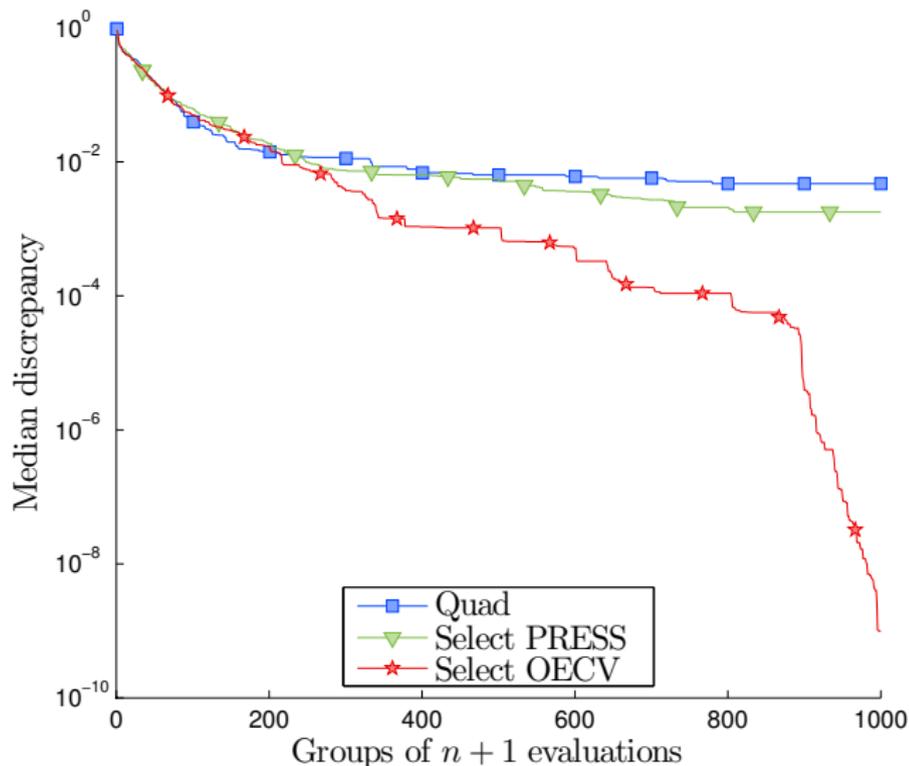
7 variables:

- ▶ Wing span
- ▶ Root chord
- ▶ Taper ratio
- ▶ Angle of attack at root
- ▶ Angle of attack at tip
- ▶ Tube external diameter
- ▶ Tube thickness

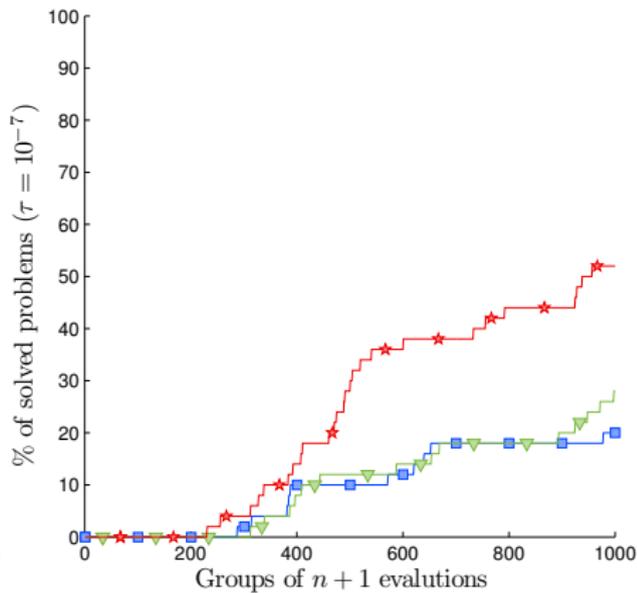
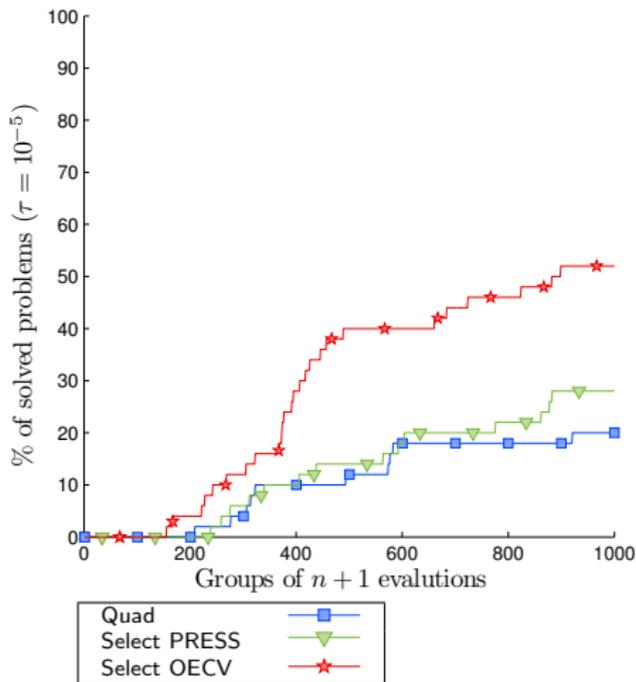


Decomposition of multidisciplinary optimization problems: Formulations and application to a simplified wing design, C. Tribes, J.F. Dubé and J.Y. Trépanier, Engineering Optimization, Vol. 37, No. 8, December 2005, 775–796

Test problem 1: MDO Simplified wing (50 runs)



Test problem 1: MDO Simplified wing (50 runs)



Test problem 2: MDO Aircraft range

Max: Aircraft Range

st: Stress $< 1.09 (\times 5)$

$0.96 < \text{Wing Twist} < 1.04$

Pressure gradient < 1.04

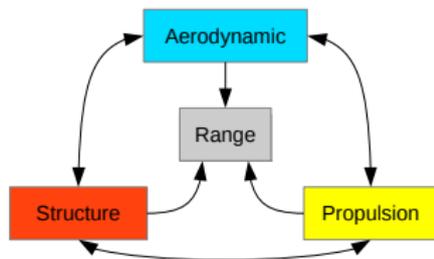
$0.5 < \text{Eng. Scale Factor} < 1.5$

Engine Temperature < 1.02

Throttle Setting $< T_{UA}$

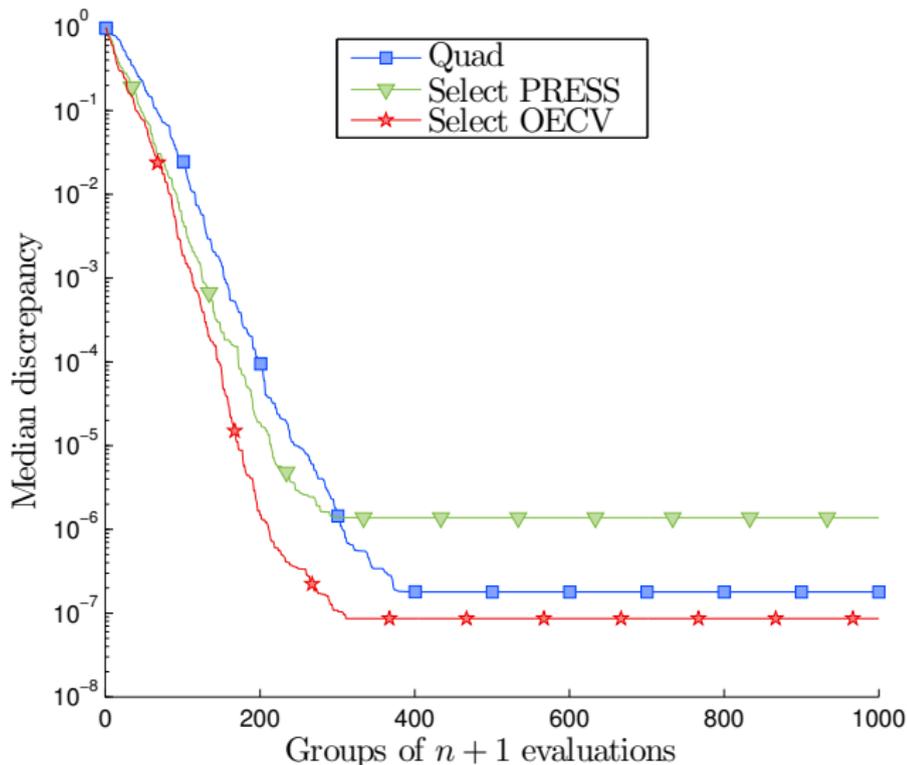
10 variables:

- ▶ Taper ratio
- ▶ Wingbox cross-section
- ▶ Thickness/chord
- ▶ Aspect ratio
- ▶ Wing surface area
- ▶ Wing sweep
- ▶ Skin friction coef.
- ▶ Throttle
- ▶ Altitude
- ▶ Mach number

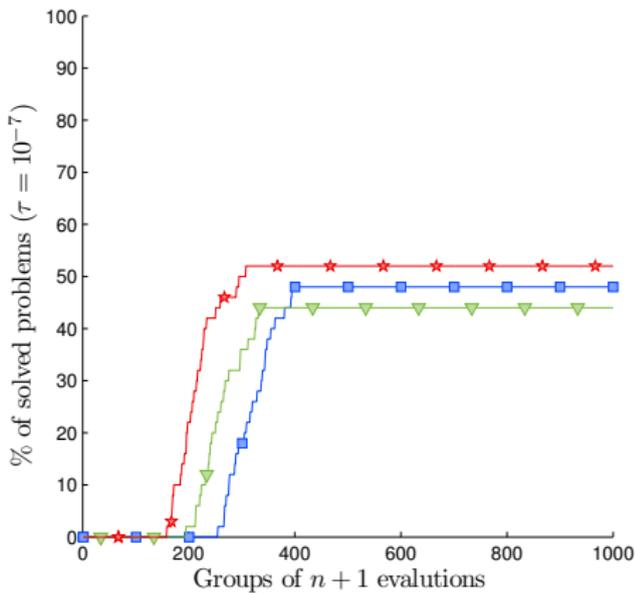
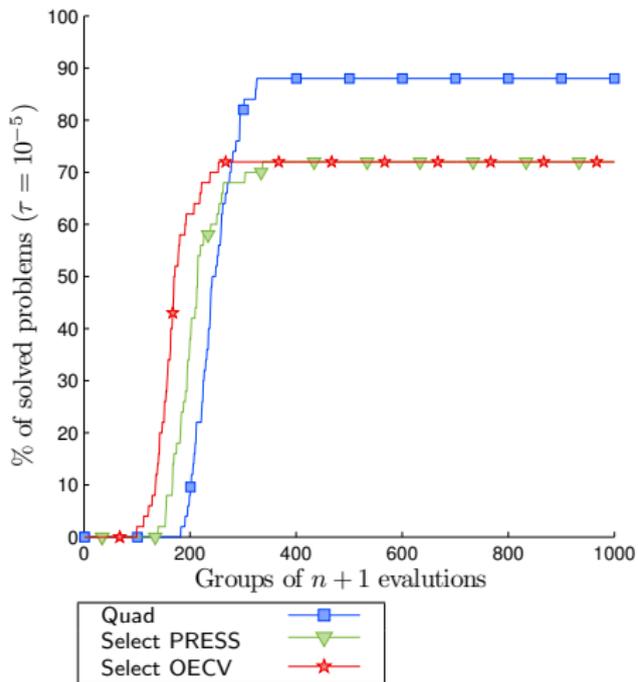


NASA/CR-2001-211053, *Multidisciplinary Aerospace Systems Optimization*, Computational AeroSciences Project, S. Kodiyalam, Lockheed Martin Space Systems Company, Sunnyvale (Ca)

Test problem 2: MDO Aircraft range (50 runs)



Test problem 2: MDO Aircraft range (50 runs)



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Discussion

- ▶ MADS + surrogate-assisted optimization: Guarantee of convergence + efficiency.
- ▶ We use **ensembles of surrogates** with **selection** based on a **metric**.
- ▶ We compare two metrics (PRESS and OECV):
 - ▶ Both based on **Cross-validation (CV)** that ensures a good quality of prediction outside of the training points.
 - ▶ Use either the **quadratic error (RMSE)** or the **order error (OE)**:
 - ▶ PRESS: CV + RMSE.
 - ▶ OECV: CV + OE.
- ▶ OECV is essentially designed to detect the best suited model for surrogate-assisted optimization.

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