

ISMP 2012

# The mesh adaptive direct search algorithm with reduced number of directions

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# Presentation outline

**Blackbox optimization problems**

**The MADS algorithm**

**Reducing the size of the poll set**

**Numerical results**

**Discussion**

## Blackbox optimization problems

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# Blackbox optimization problems

We consider the optimization problem:

$$\min_{x \in \Omega} f(x)$$

where evaluations of  $f$  and the functions defining  $\Omega$  are usually the result of a computer code (a blackbox).

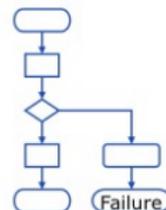
# Blackboxes as illustrated by J. Simonis [ISMP 2009]



Long runtime



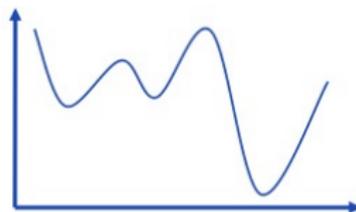
Large memory  
requirement



Software  
might fail



No derivatives  
available



Local  
optima



Non-smooth,  
noisy

Blackbox optimization problems

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## The MADS acronyms

- ▶ **MADS** (**M**esh **A**daptive **D**irect **S**earch)
  - The algorithmic framework without the definition of the polling directions.
- ▶ **LT-MADS**: Original MADS implementation.
- ▶ **Ortho-MADS**: Second MADS implementation.
- ▶ **NOMAD** (**N**onlinear **O**ptimization with the **MADS** algorithm):
  - The software package. Includes LT-MADS and Ortho-MADS.

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- ▶ **NOMAD** (**N**onlinear **O**ptimization with the **MADS** algorithm):
  - The software package. Includes LT-MADS and Ortho-MADS.
- ▶ NOMADS does not exist.

## Mesh Adaptive Direct Search (MADS)

- ▶ Audet and Dennis [SIOPT, 2006]
- ▶ Iterative algorithm that evaluates the blackbox at some **trial points** on a spatial discretization called the **mesh**.
- ▶ One iteration = **search** and **poll**.
- ▶ The search allows trial points generated anywhere on the mesh.
- ▶ The poll consists in generating a list of trial points constructed from **poll directions**. These directions grow dense.
- ▶ At the end of the iteration, the mesh size is reduced if no new iterate is found.
- ▶ Algorithm is backed by a **convergence analysis** based on the Clarke Calculus for nonsmooth functions.

## The poll (1/2)

### ► Mesh at iteration $k$ :

$$\text{► } M_k = \bigcup_{x \in V_k} \{x + \Delta_k D z : z \in \mathbb{N}^{n_D}\}.$$

►  $V_k$  is the “cache”.

►  $\Delta_k > 0$  is the **mesh size parameter**.

►  $D$  is a fixed set of directions typically set to  $[I \ -I]$ .

► **Poll directions:** A positive spanning set  $D_k \subset \mathbb{R}^n$  where each direction  $d \in D_k$  can be written as a nonnegative integer combination of directions of  $D$ .

► The directions correspond typically to a **minimal positive basis** ( $n + 1$  directions) or a **maximal positive basis** ( $2n$  directions).

## The poll (2/2)

- ▶ **Poll set:**  $P_k = \{x_k + \Delta_k d : d \in D_k\}$  where  $x_k$  is the current incumbent, or the **poll center**.
- ▶ The trial points in  $P_k$  are evaluated following the **opportunistic strategy**: evaluations are interrupted as soon as a new better solution is found.
- ▶ **Trial points ordering** is then crucial in practice. It can be based on:
  - ▶ Model or surrogate values.
  - ▶ Angle with the gradient of a model.
  - ▶ Angle with the last direction of success.
  - ▶ etc.

**[0] Initializations**  $(x_0, \Delta_0)$

**[1] Iteration**  $k$

**[1.1] Search**

select a finite number of mesh points  
 evaluate candidates opportunistically

**[1.2] Poll** (if the Search failed)

construct poll set  $P_k = \{x_k + \Delta_k d : d \in D_k\}$   
 sort( $P_k$ )  
 evaluate candidates opportunistically

**[2] Updates**

if success

$x_{k+1} \leftarrow$  success point  
 increase  $\Delta_k$

else

$x_{k+1} \leftarrow x_k$   
 decrease  $\Delta_k$

$k \leftarrow k + 1$ , stop or go to **[1]**

## Motivation

- ▶ MADS is a generic algorithmic framework with two practical implementations: LT-MADS and Ortho-MADS.
- ▶ For various reasons, Ortho-MADS is preferred to LT-MADS. LT-MADS defines  $n + 1$  and  $2n$  types of directions, and Ortho-MADS has only the  $2n$  variant:

	LT-MADS(2006)	Ortho-MADS (2009)
$n + 1$	✓	✗
$2n$	✓	✓

- ▶ Some tests suggest that the LT-MADS implementation is more efficient with  $n + 1$  directions. We want to define an **Ortho-MADS variant using  $n + 1$  directions.**

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## General framework (1)

**Idea:** Given a poll set of  $2n$  trial points, prune it to  $n$  points and add a direction to obtain  $n + 1$  points.

### Poll at iteration $k$

$P_k^o = \{x_k + \Delta_k d : d \in D_k^o\}$  (original poll set)

extract  $D'_k \subset D_k^o$

compute new direction  $d_k$

$D_k = D'_k \cup \{d_k\}$

construct  $P_k = \{x_k + \Delta_k d : d \in D_k\}$  (reduced poll set)

sort( $P_k$ )

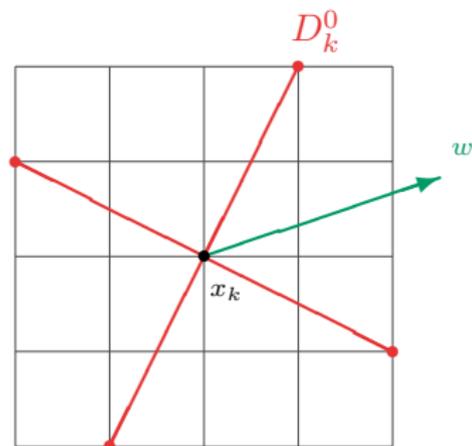
evaluate( $P_k$ ) (opportunistically)

**Ortho-MADS**  $n + 1$  is a simple first implementation of this general framework.

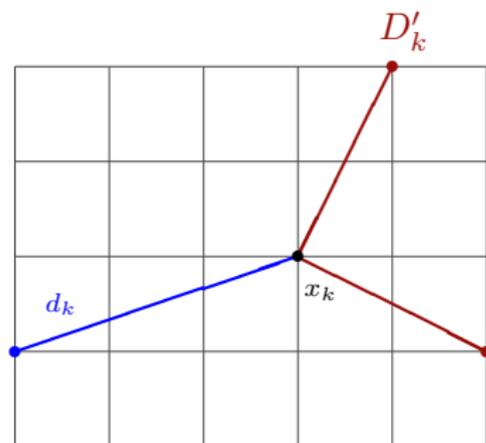
## Ortho-Mads $n + 1$

- ▶  $D_k^o = [H_k \quad -H_k]$  is the original Ortho-MADS spanning set with  $2n$  directions and  $H_k \in \mathbb{Z}^{n \times n}$  an orthogonal basis with integer coefficients.
- ▶ The selection of  $n$  columns of  $D_k^o$  to obtain  $D_k'$  is based on a target direction  $w \in \mathbb{R}^n$ .
- ▶ The target direction is taken as the last direction of success.
- ▶ The  $(n + 1)$ th direction is  $d_k = - \sum_{d \in D_k'} d$ .

## Ortho-MADS $n + 1$ : Idea



$2n$  directions  $D_k^0$



$n + 1$  directions  $D_k = D'_k \cup \{d_k\}$

## Completion using function values

- ▶ We now present a second and more general framework.
- ▶ This version is not limited to Ortho-MADS and may be applied to any poll sets. For example hybrid versions with more than  $2n$  points.
- ▶ The first framework is decomposed allowing to evaluate  $n$  trial points in a first step and possibly one last  $(n + 1)$ th point  
 $y_k = x_k + d_k \Delta_k$ .
- ▶  $y_k$  is constructed by exploiting the function values at the first  $n$  points.
- ▶  $y_k$  must lie on the mesh and  $d_k$  must be inside the cone of the negative directions of  $D'_k$  so that the poll directions remain a positive spanning set.

## General framework (2)

### Poll at iteration $k$

$P_k^o = \{x_k + \Delta_k d : d \in D_k^o\}$  (original poll set)

extract  $D'_k \subset D_k^o$  and construct  $P'_k$

sort ( $P'_k$ )

evaluate ( $P'_k$ ) (opportunistically)

Success

| interrupt iteration

Failure

| compute new direction  $d_k$

| evaluate ( $x_k + \Delta_k d_k$ )

## Use of quadratic models

Quadratic models may be used at two different levels:

1. In **Ortho-MADS**  $n + 1$ : The simplex gradient is taken as the target direction  $w$ .
2. In **Framework (2)**: Optimize a model to determine the last trial point  $y_k = x_k + \Delta_k d_k$ .

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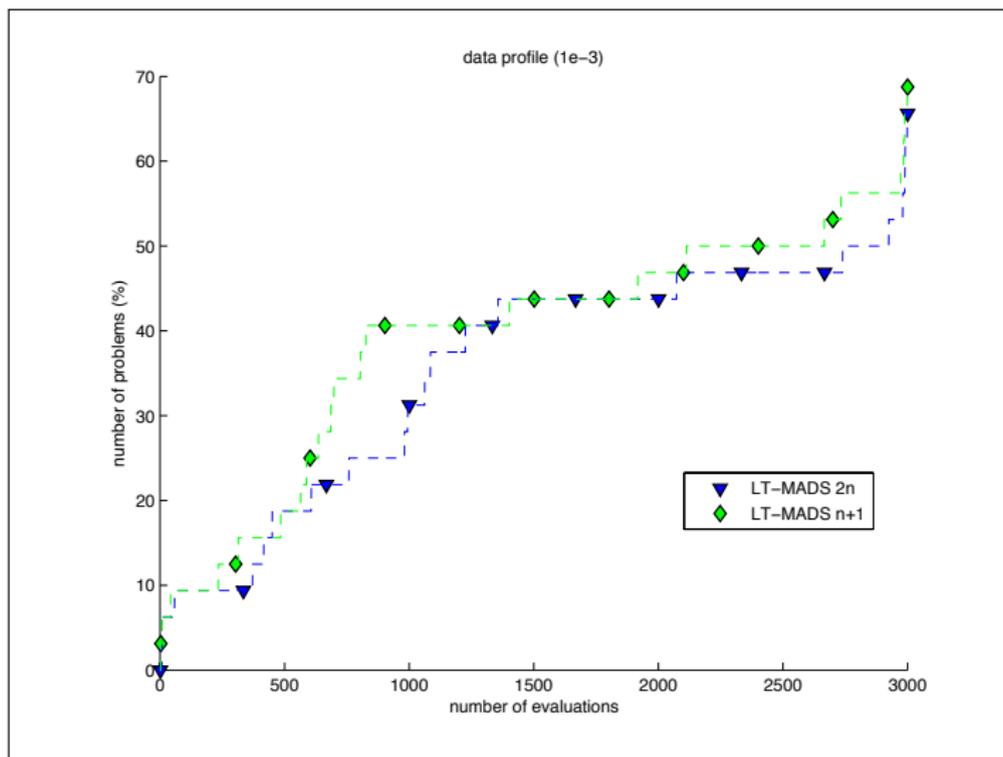
## Set of problems and conditions

- ▶ These are **preliminary tests**.
- ▶ 32 analytic problems from the DFO literature.
- ▶ Number of variables:  $n$  ranges from 2 to 12.
- ▶ Constraints: 7 problems have from 1 to 15 constraints.
- ▶ A budget of 3000 evaluations is considered.
- ▶ Results are illustrated by **data profiles** with a precision of  $10^{-3}$ .

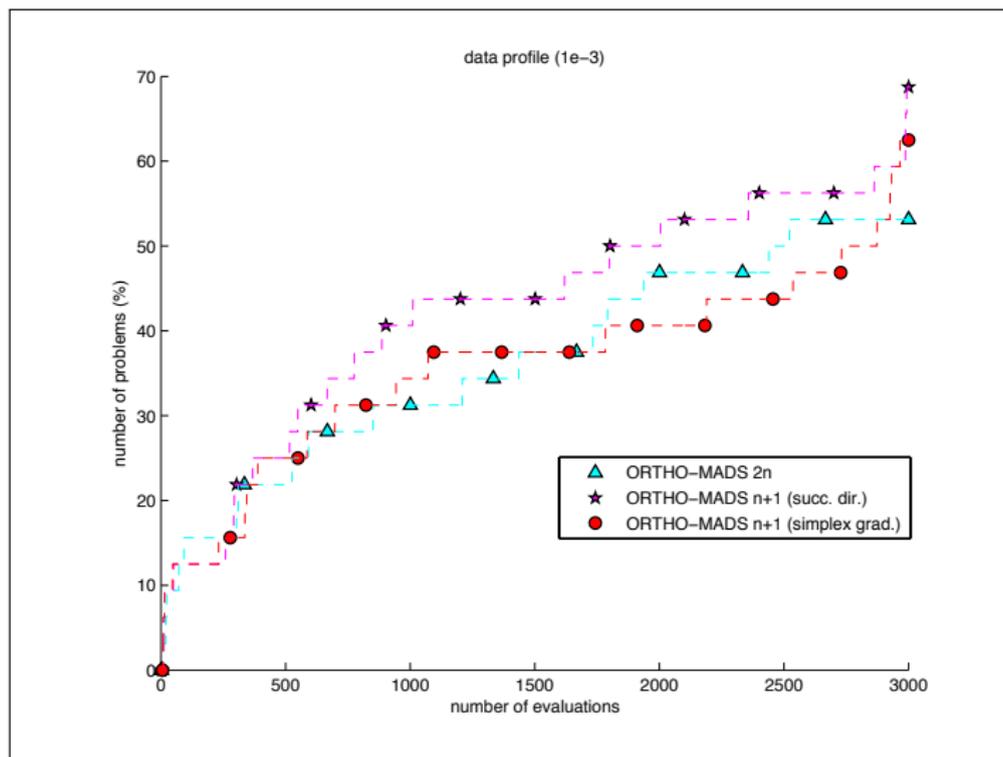
## Summary of the tests

1. LT-MADS  $2n$  vs  $n + 1$ .
2. Ortho-MADS  $2n$  vs Ortho-MADS  $n + 1$  with two variants:  $w$  success direction or simplex gradient.
3. LT-MADS vs Ortho-MADS.

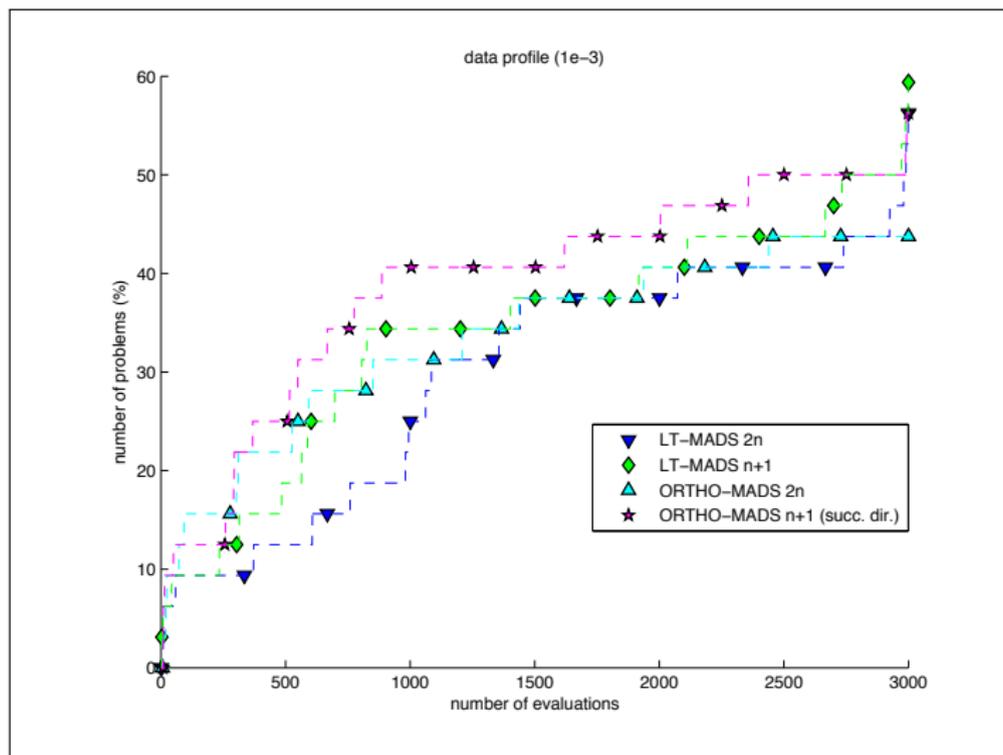
# 1. LT-MADS $2n$ vs $n + 1$



## 2. Ortho-MADS $2n$ vs $n + 1$



### 3. LT-MADS vs Ortho-MADS



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## Discussion

- ▶ This work is based on the remark that using minimal positive bases instead of maximal positive bases seems preferable.
- ▶ It defines several methods in order to achieve the reduction of poll directions from  $2n$  to  $n + 1$  points.
- ▶ Preliminary tests demonstrate significant improvements.
- ▶ Future work includes more testing on true applications and development of smarter ways to use quadratic models and to treat the constraints.
- ▶ Our blackbox optimization solver: [www.gerad.ca/nomad](http://www.gerad.ca/nomad).